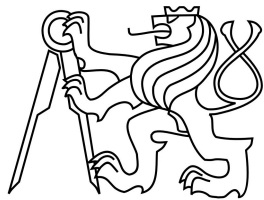


Latest AI Developments Explained (OpenAI SORA, World Models, Q*)

Pavel Kordík

Department of Applied Mathematics,
Faculty of Information Technology,
Czech Technical University in Prague



Machine Learning and
Computational Intelligence Group

SORA by Open AI

- Text to video LLM
 - Released on February 15, 2024
 - Simulator of the physical world
 - Natural language understanding
 - Story, video, sound generation
 - Transformers, World models, Latent diffusion, ...

- Example text prompt:

This close-up shot of a chameleon showcases its striking color changing capabilities. The background is blurred, drawing attention to the animal's striking appearance.

SORA by Open AI



What makes this possible?

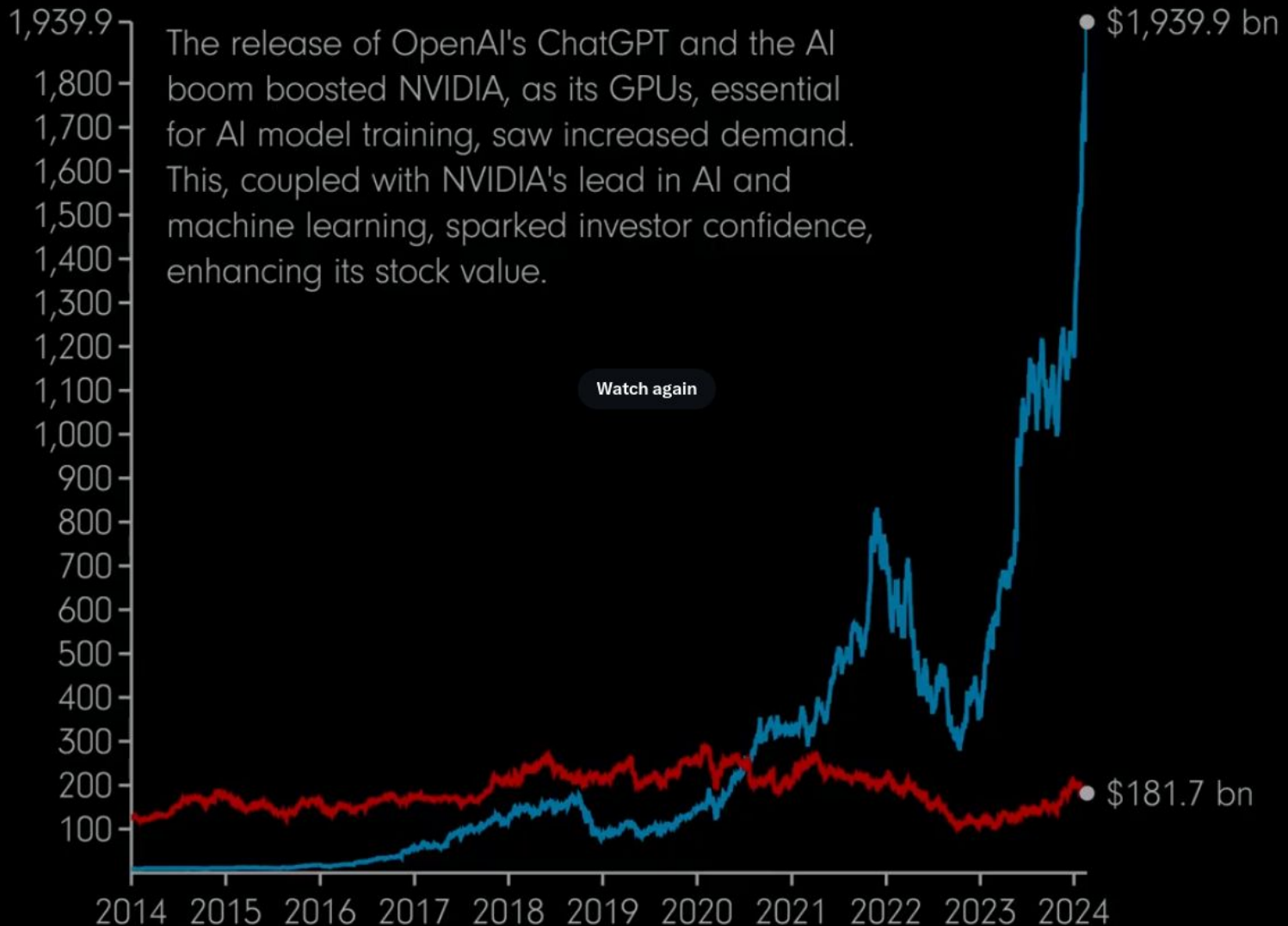
- **Massive compute**
- Massive datasets
- Massive human effort
 - Researching new algorithms
 - Data preparation, benchmarks
 - Foundational model training
 - Model alignment
 - Model productization (in progress for SORA)

NVIDIA versus Intel

Market capitalisation, US\$ billions

— NVIDIA — Intel

22 Feb 2024



What makes this possible?

- Massive compute
- **Massive datasets**
- Massive human effort
 - Researching new algorithms
 - Data preparation, benchmarks
 - Foundational model training
 - Model alignment
 - Model productization (in progress for SORA)

What was Sora trained on? Creatives demand answers.

We think we know, but OpenAI refuses to tell us.



Justine Bateman
@JustineBateman



Every nanosecond of this #AI garbage is trained on stolen work by real artists. Repulsive.

 **OpenAI**  @OpenAI · Feb 15

Introducing Sora, our text-to-video model.

<https://openai.com/blog/data-partnerships>

What makes this possible?

- Massive compute
- Massive datasets
- **Massive human effort**
 - Researching new algorithms
 - Data acquisition, curation, benchmarks
 - Foundational model training
 - Model alignment
 - Model productization (in progress for SORA)

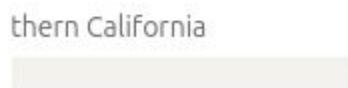
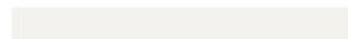
Just OpenAI - from 45 people in 2017 ...

1,701 associated members



Search employees by title, keyword or school

d + Add



What they do



What they are skilled a



What made SORA possible?

Research perspective

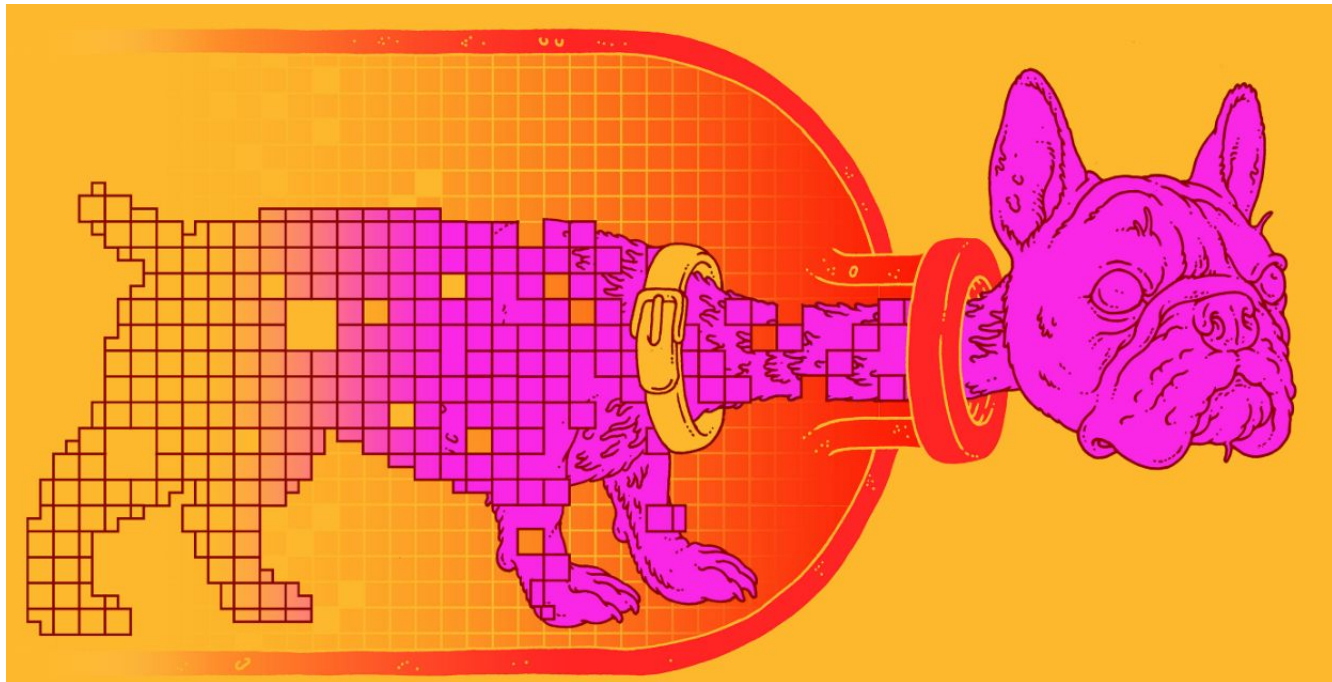
- Self-supervised training
- Understanding as compression
- Neural autoencoders
- Diffusion models
- Vision transformers
- Latent diffusion transformers
- World models

Self-supervised training

- Labels not needed
- Massive data available - text, images, sound, videos
- Learning tasks:
 - Masked modeling
 - Next sentence prediction
- Standard optimization methods available
 - SGD, ADAM, BackProp, ...

Understanding as compression

- Preserve important information, Generalize, Predict
- Various forms of information bottlenecks

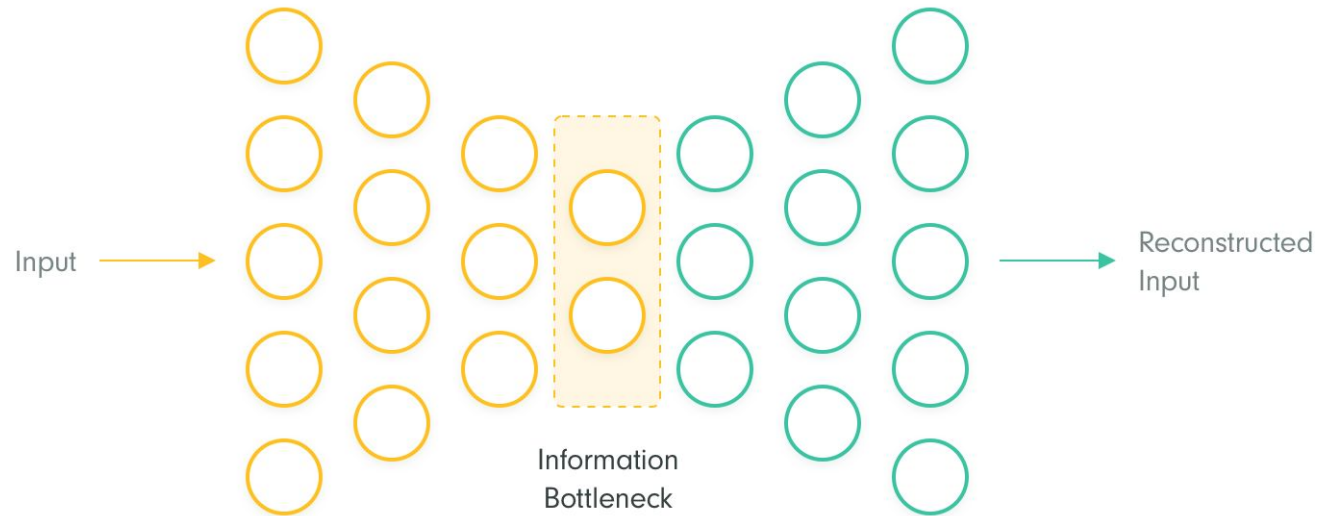


<https://mural.maynoothuniversity.ie/10327/1/PM-Understanding-2016.pdf>

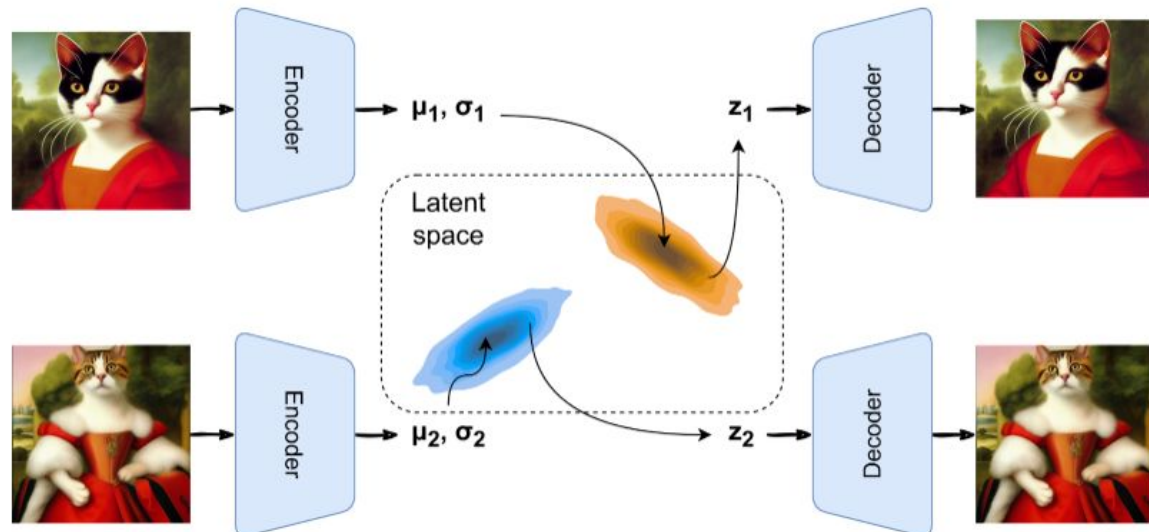
<https://link.springer.com/article/10.1007/s11098-018-1152-1>

Neural compression - AE, VAE

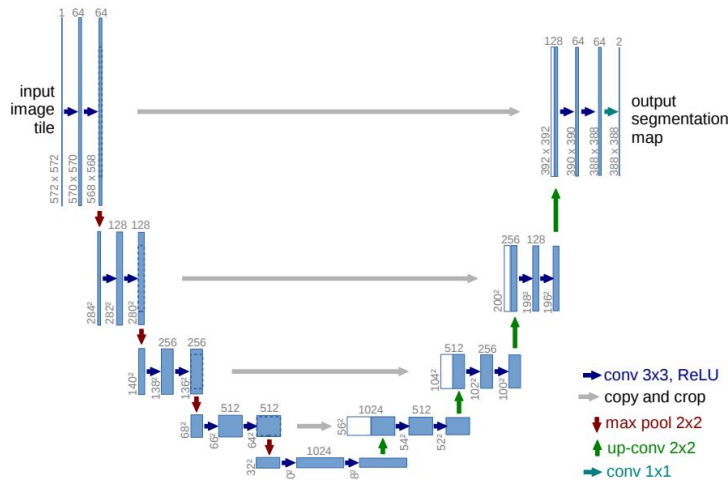
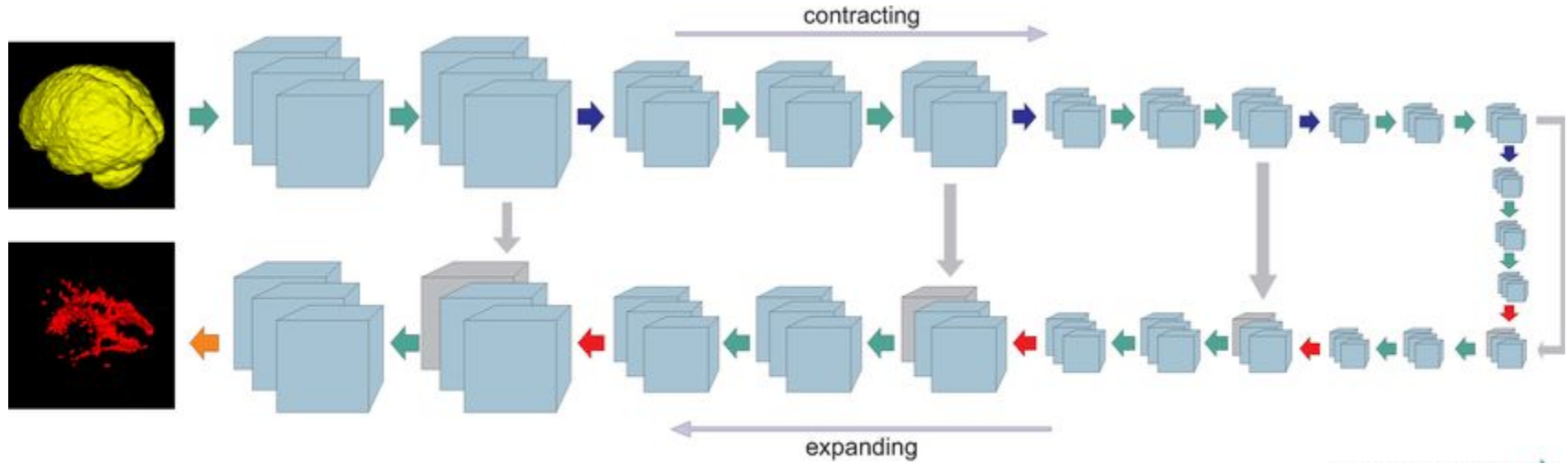
Auto Encoder (AE)



Variational Auto Encoder (VAE)



Neural compression - UNet



U-Net: Convolutional Networks for Biomedical Image Segmentation:

<https://arxiv.org/pdf/1505.04597.pdf>

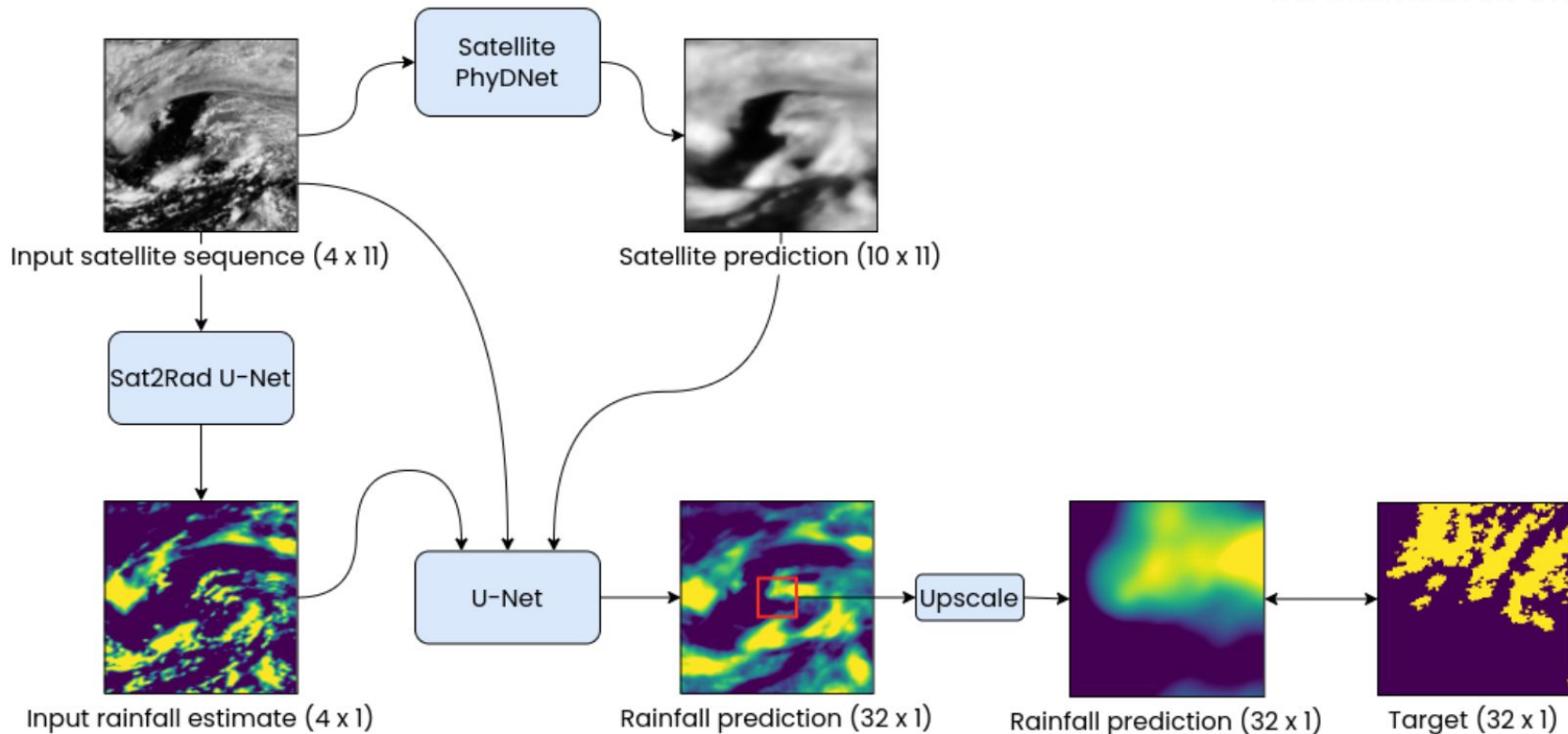
see also Hourglass networks:

<https://arxiv.org/pdf/1603.06937.pdf>

UNets are quite useful

WeatherFusionNet (WFN)

3 networks trained separately



Diffusion models

Adding gaussian noise

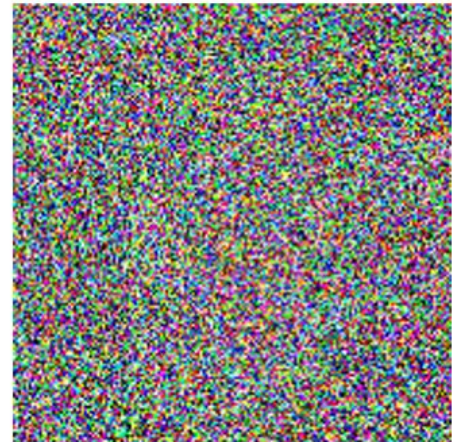
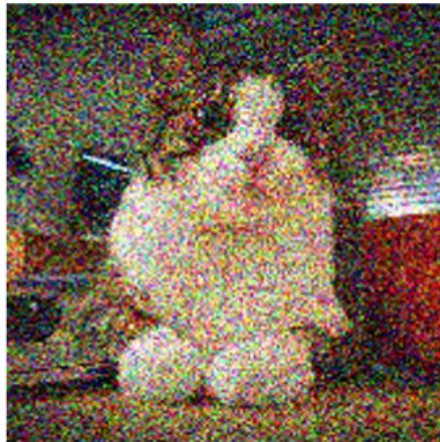
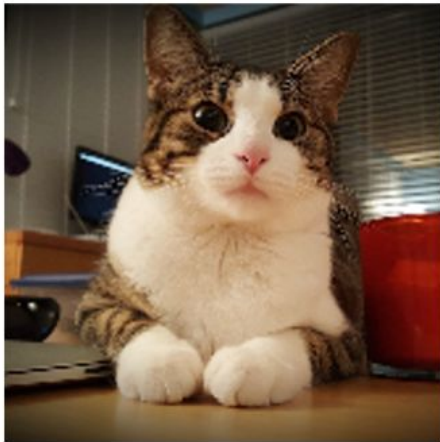
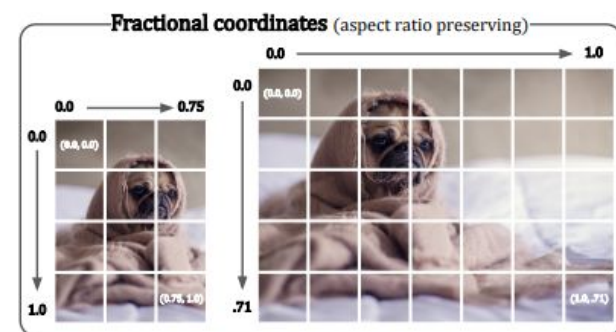
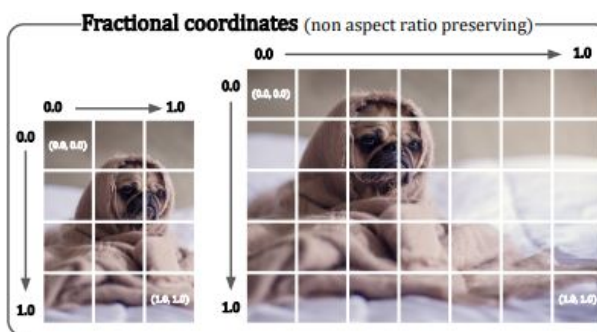
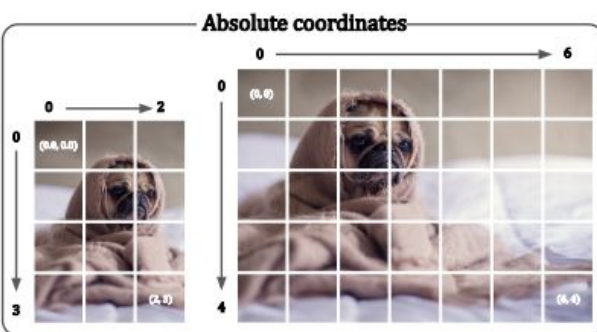
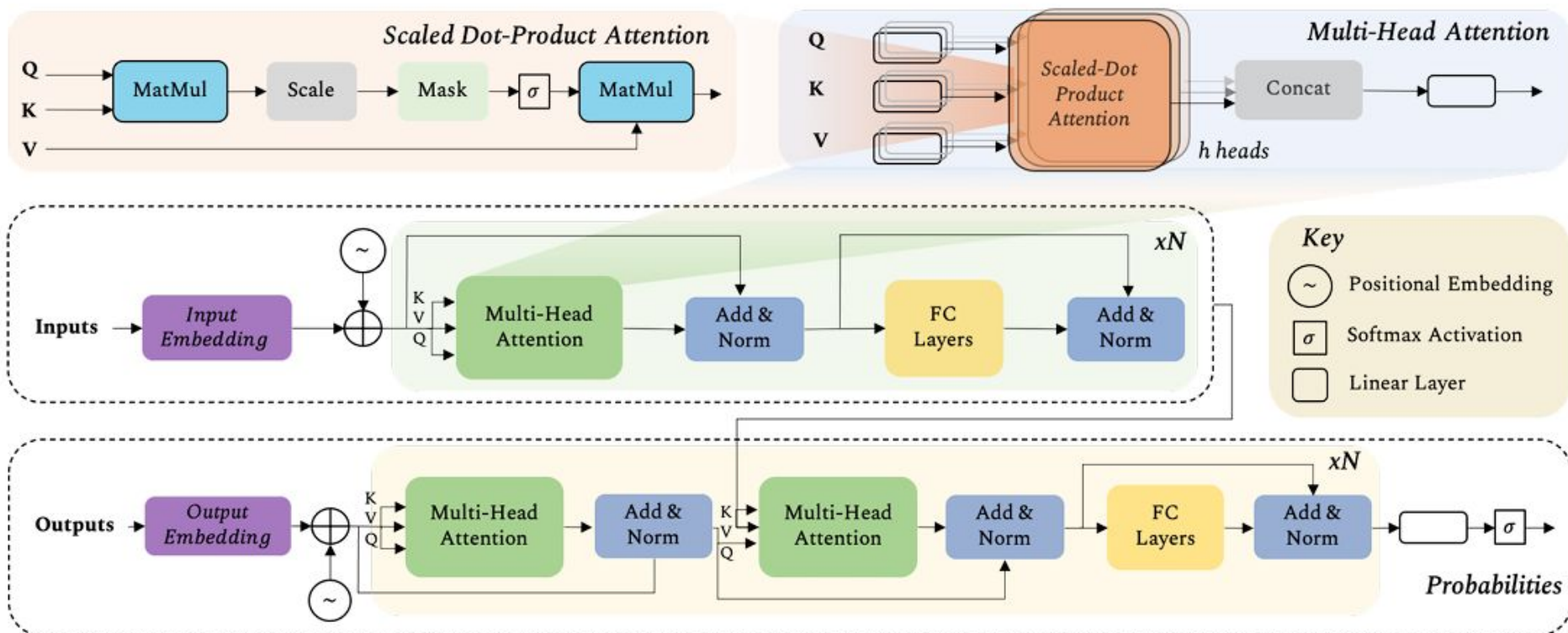
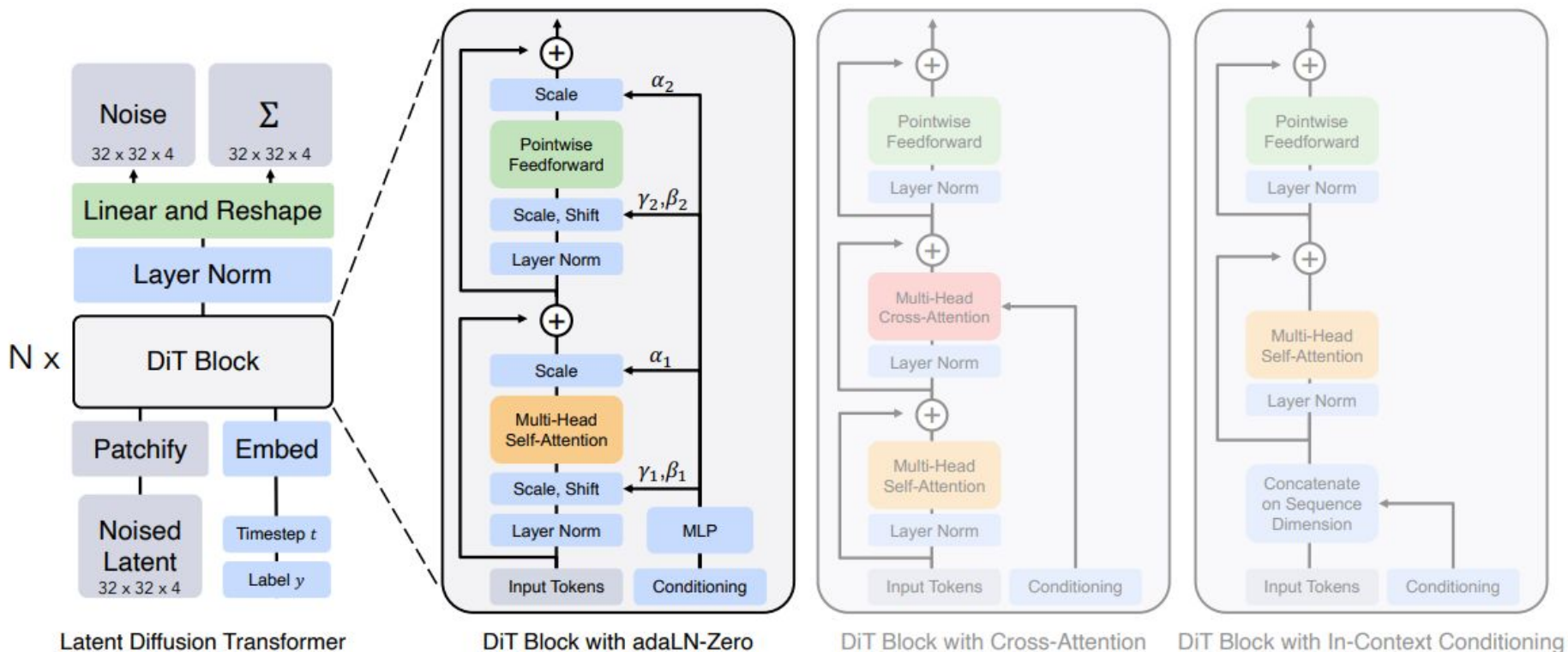


Image denoising process (remember masked modeling?)

Vision transformers



Latent diffusion transformers



https://openaccess.thecvf.com/content/ICCV2023/papers/Peebles_Scalable_Diffusion_Models_with_Transformers_ICCV_2023_paper.pdf

World models

At each time step, our agent receives an **observation** from the environment.

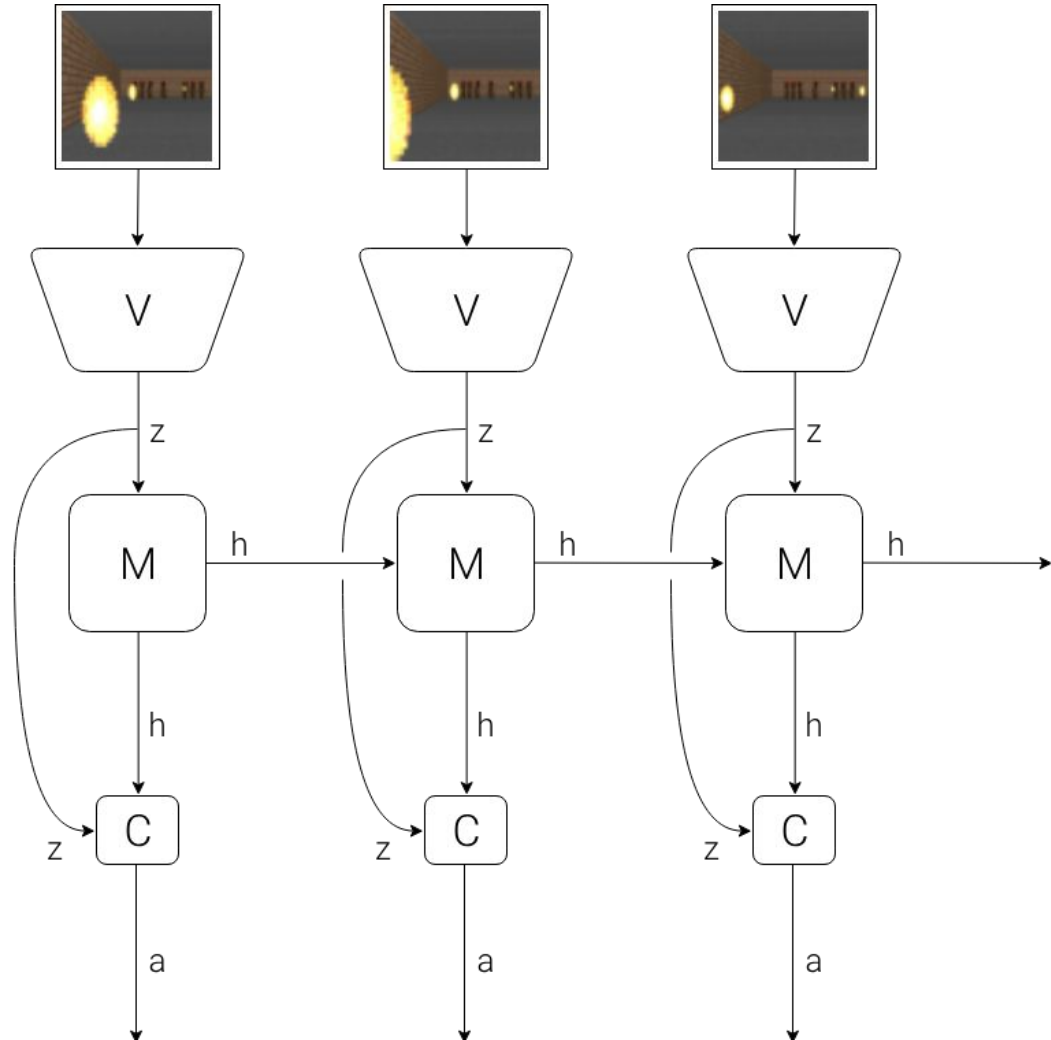
World Model

The **Vision Model (V)** encodes the high-dimensional observation into a low-dimensional latent vector.

The **Memory RNN (M)** integrates the historical codes to create a representation that can predict future states.

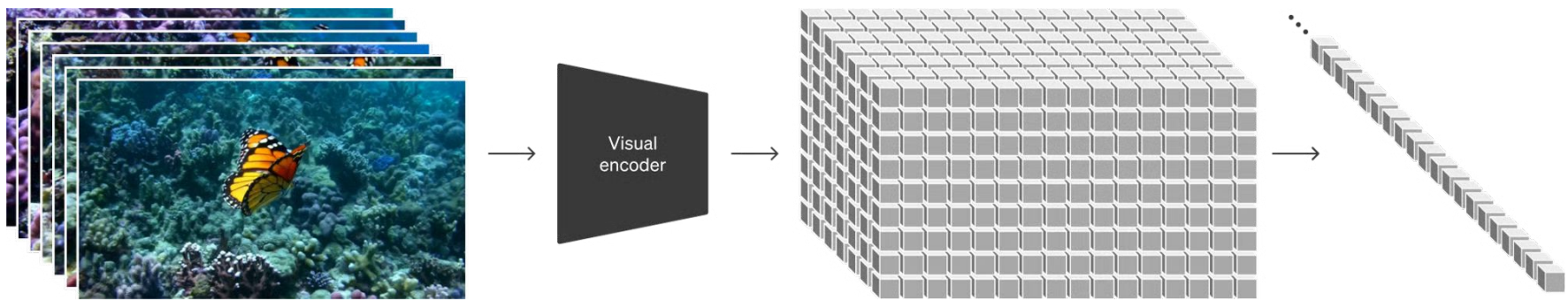
A small **Controller (C)** uses the representations from both **V** and **M** to select good actions.

The agent performs **actions** that go back and affect the environment.



<https://worldmodels.github.io/>

SORA: Video generation models as world simulators



“...transformer architecture that operates on spacetime patches of video and image latent codes...”

EMO - Generating Expressive Portrait Videos with Audio2Video Diffusion



EMO: Emote Portrait Alive - Generating Expressive Portrait Videos with Audio2Video Diffusion Model under Weak Conditions

*LinRui Tian, Qi Wang, Bang Zhang, Liefeng Bo
Institute for Intelligent Computing, Alibaba Group*

<https://arxiv.org/pdf/2402.17485.pdf>

SORA, EMO as Foundation models?

[Google Gemma, Gemini 1.5 Pro](#)

Foundation Models

 [LMSYS Chatbot Arena Leaderboard](#)

[Vote](#) | [Blog](#) | [GitHub](#) | [Paper](#) | [Dataset](#) | [Twitter](#) | [Discord](#)

LMSYS [Chatbot Arena](#) is a crowdsourced open platform for LLM e

Rank	Model	Ave
1	GPT-4-1106-preview	1254
2	GPT-4-0125-preview	1253
3	Bard...(Gemini_Pro)	1218
4	GPT-4-0314	1191
5	GPT-4-0613	1164
6	Mistral_Medium	1152
7	Claude-1	1150
8	Qwen1.5-72B-Chat	1147
9	Claude-2.0	1132
10	Gemini_Pro...(Dev_API)	1122
11	Claude-2.1	1120
12	Mixtral-8x7b-Instruct-v0.1	1120

Learn more about Google's foundation models that include text-to-image, text-to-code and speech-to-text.

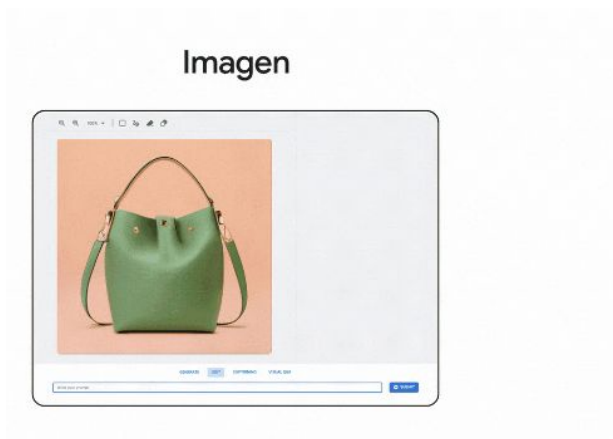


Imagen Model Family

Unlocking visual creativity

Imagen is our family of image generation and editing n build on advances in large Transformer language mode models. This family of models is being incorporated int products, including: Image generation in Google Slides Android's Generative AI wallpaper.

Imagen is a text-to-image model with a high degree o

[Gov.uk initial report on foundational models](#)

[Governing open foundational models](#)

[CS 886: Recent Advances on Foundation Models](#)

What is next in AI research?



OpenAI board warned Project Q* could 'threaten humanity' prior to Sam Altman's sacking

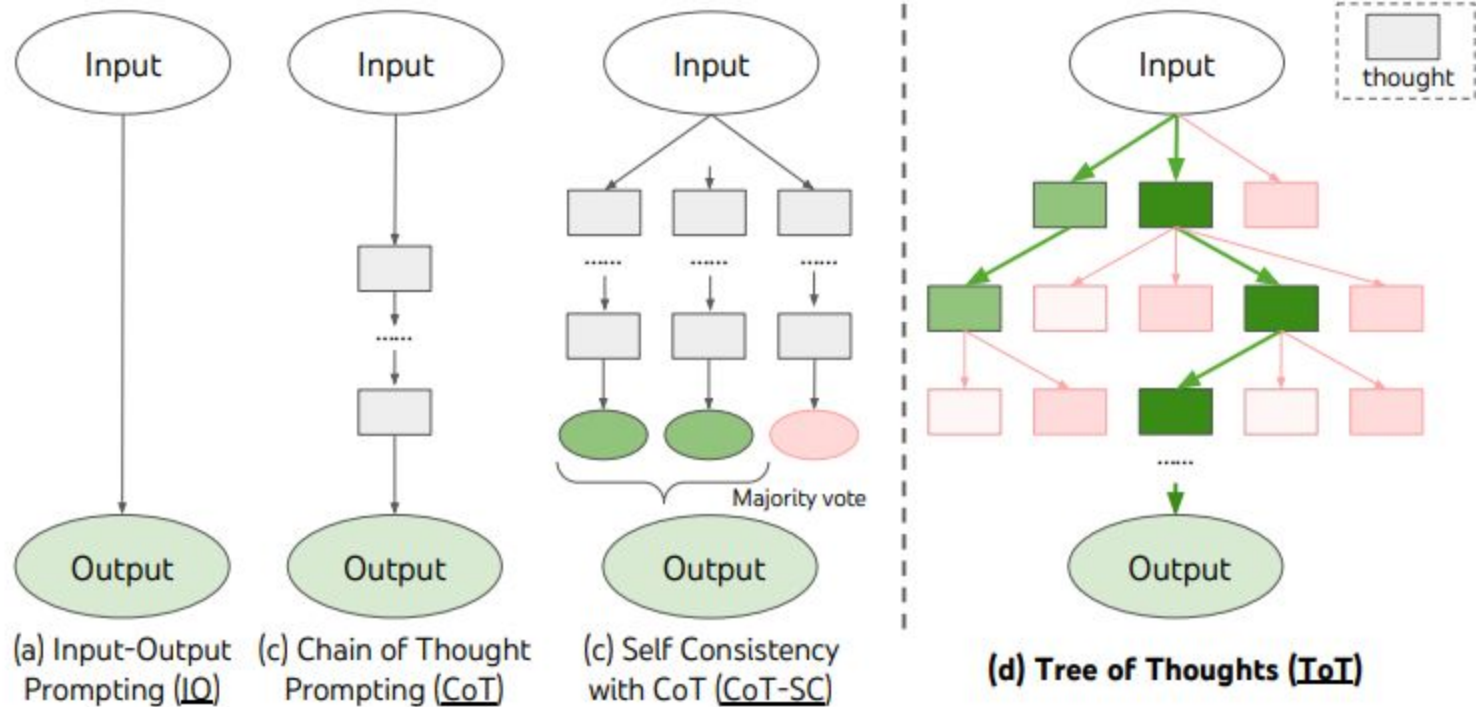
Newest algorithm is said to have solved simple maths problems – a major step forward for AI

Matthew Field

23 November 2023 • 12:36pm



Some speculations ...

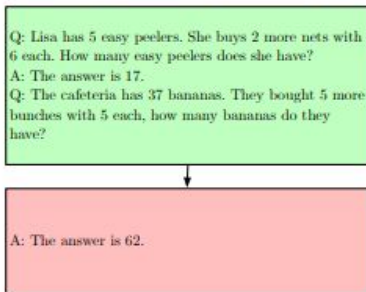


[Tree of Thoughts: Deliberate Problem Solving with Large Language Models](#)

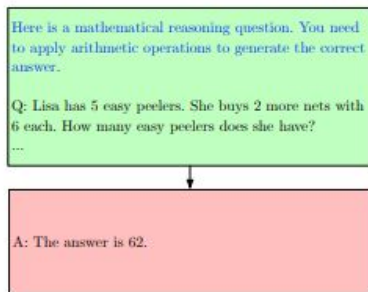
4. Search algorithm. Finally, within the ToT framework, one can plug and play different search algorithms depending on the tree structure. We explore two relatively simple search algorithms and leave more advanced ones (e.g. A* [11], MCTS [2]) for future work:

Single-Turn Prompting

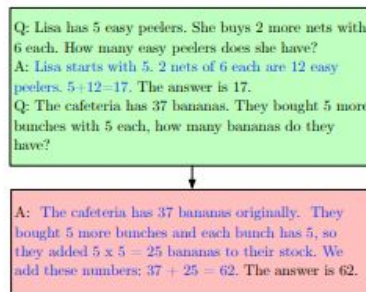
In-Context Learning



Instruction-Following

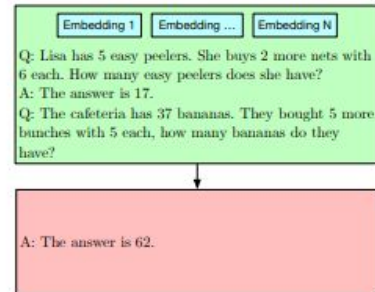


Chain-of-Thought



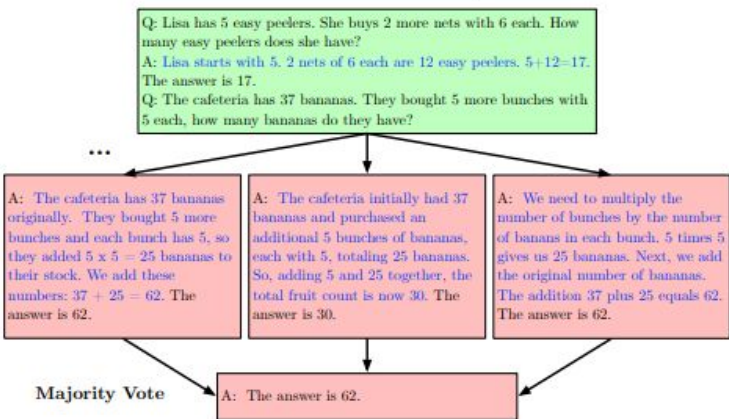
Input → Output

Prompt tuning

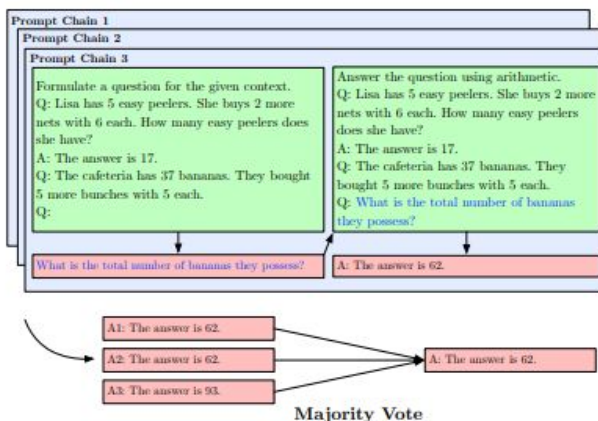


Multi-Turn Prompting

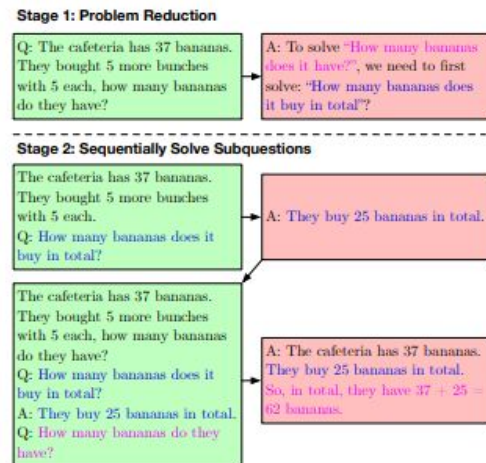
Self-Consistency



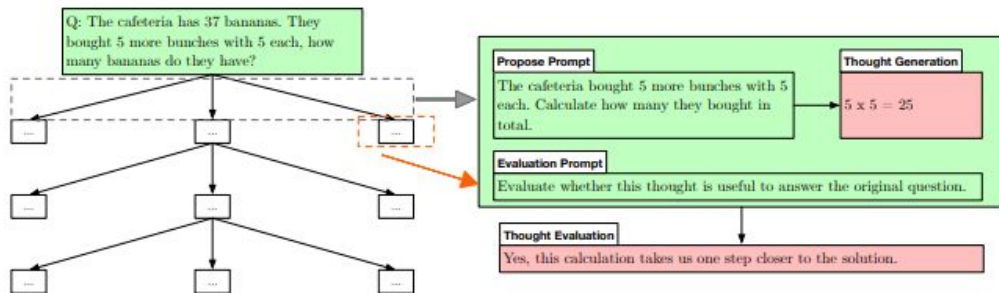
Ask-Me-Anything



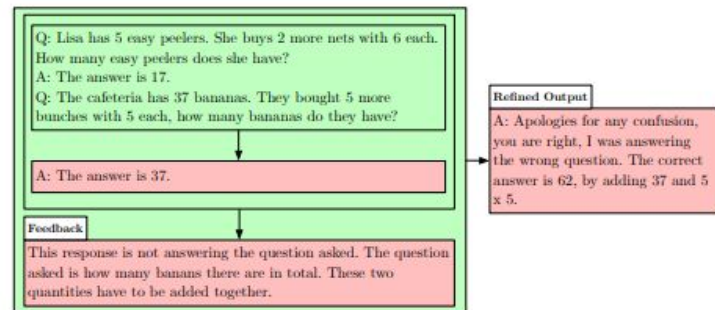
Least-To-Most



Tree of Thoughts



Self-Refine



Path towards Super-intelligence and AGI



What is needed?

- Memory augmented models
- Planning and reasoning - blend with reinforcement learning?
- Better training datasets
- Better learning from human feedback
- Better benchmarks
- Open ended learning?

Memory augmented LLMs are computationally universal

We show that transformer-based large language models are computationally universal when augmented with an external memory. Any deterministic language model that conditions on strings of bounded length is equivalent to a finite automaton, hence computationally limited. However, augmenting such models with a read-write memory creates the possibility of processing arbitrarily large inputs and, potentially, simulating any algorithm. We establish that an existing large language model, Flan-U-PaLM 540B, can be combined with an associative read-write memory to exactly simulate the execution of a universal Turing machine, $U_{15,2}$. A key aspect of the finding is that it does not require any modification of the language model weights. Instead, the construction relies solely on designing a form of stored instruction computer that can subsequently be programmed with a specific set of prompts.

	A	B	C	D	E	F	G	H
0	0, +, B	1, +, C	0, -, G	0, -, F	1, +, A	1, -, D	0, +, H	1, -, I
1	1, +, A	1, +, A	0, -, E	1, -, E	1, -, D	1, -, D	1, -, G	1, -, G
	I	J	K	L	M	N	O	
0	0, +, A	1, -, K	0, +, L	0, +, M	0, -, B	0, -, C	0, +, N	
1	1, -, J	halt	1, +, N	1, +, L	1, +, L	0, +, O	1, +, N	

Table 1: Transition table for the universal Turing machine $U_{15,2}$. Rows are indexed by the read symbol σ , columns are indexed by the state q , and each table entry (σ', m, q') specifies the write symbol σ' , the tape head move $m \in \{-1, +1\}$, and the next state q' .

AlphaGO Zero (2017)

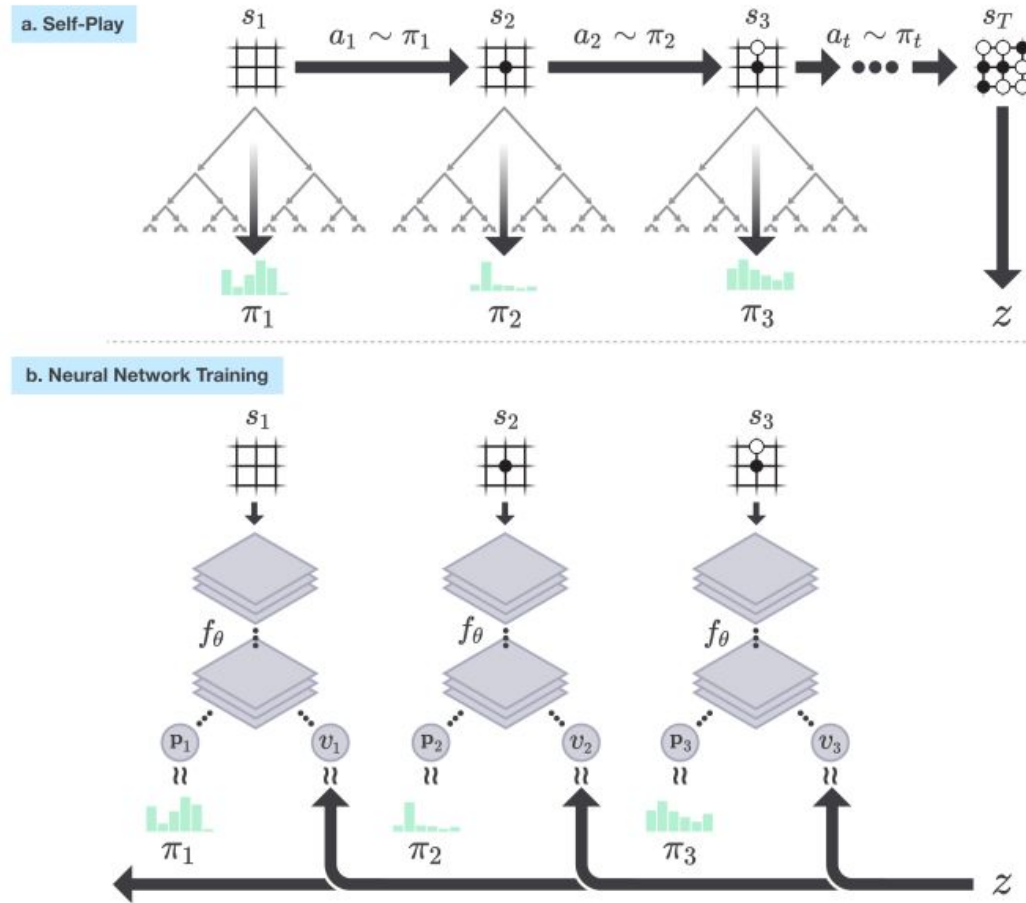
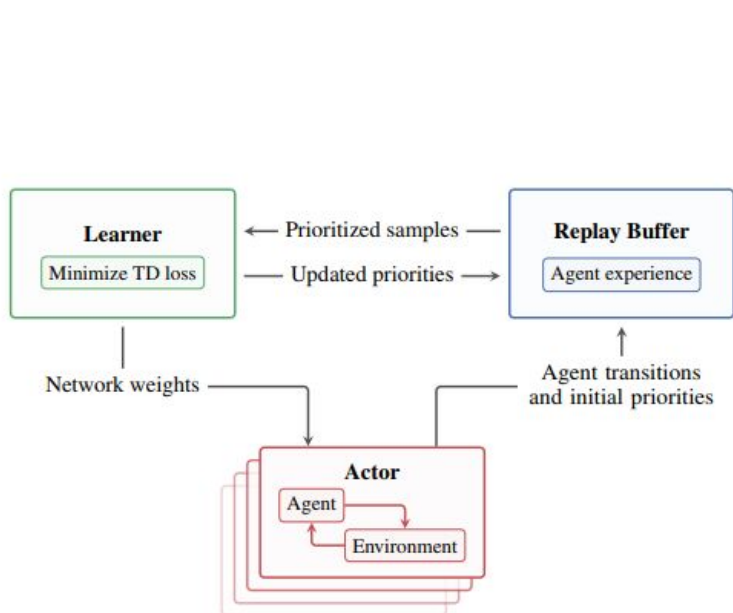
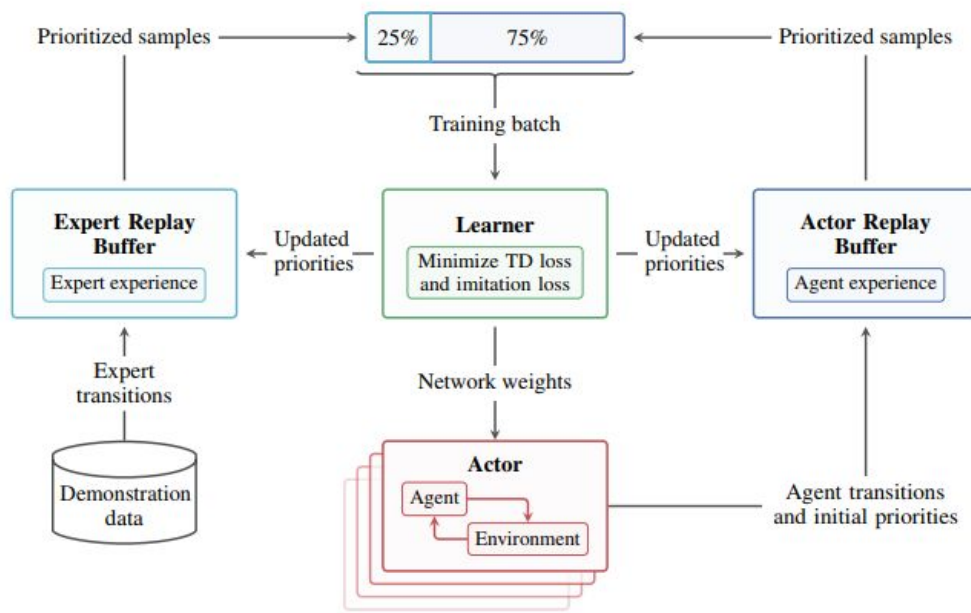


Figure 1: Self-play reinforcement learning in *AlphaGO Zero*. **a** The program plays a game s_1, \dots, s_T against itself.

Observe and Look Further (2018)



(a) Ape-X DQN



(b) Ape-X DQfD (ours)

... we ease the exploration problem by using human demonstrations that guide the agent towards rewarding states ...

Machine Theory of Mind (2018)

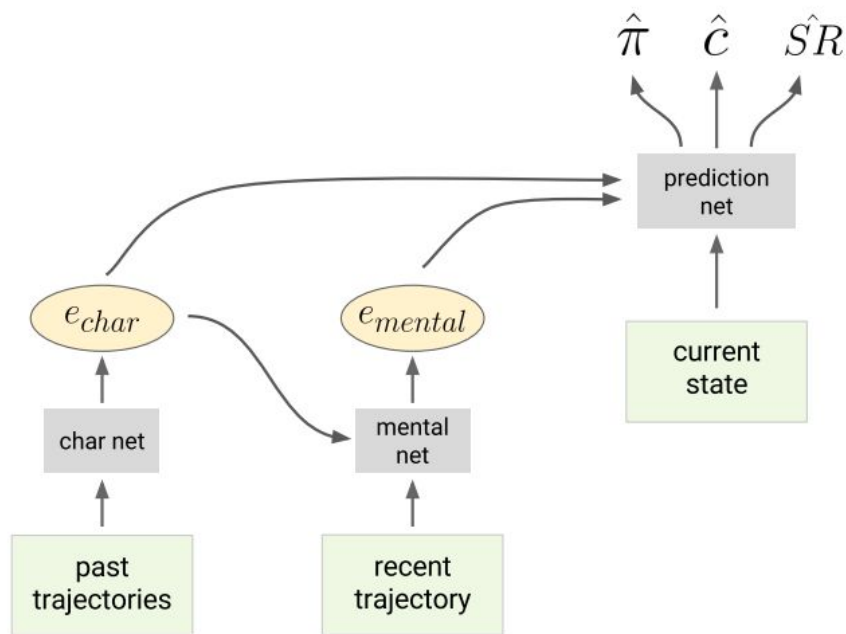


Figure 1. ToMnet architecture. The *character net* parses an agent’s past trajectories from a set of POMDPs to form a character embedding, e_{char} . The *mental state net* parses the agent’s trajectory on the current episode, to form an embedding of its mental state, e_{mental} . These embeddings are fed into the *prediction net*, which is then queried with a current state. This outputs predictions about future behaviour, such as next-step action probabilities ($\hat{\pi}$), probabilities of whether certain objects will be consumed (\hat{c}), and predicted successor representations (\hat{SR} ; Dayan, 1993).

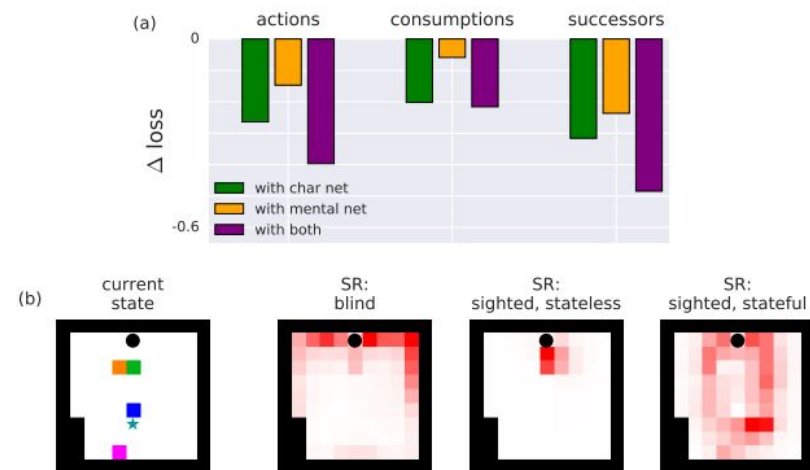
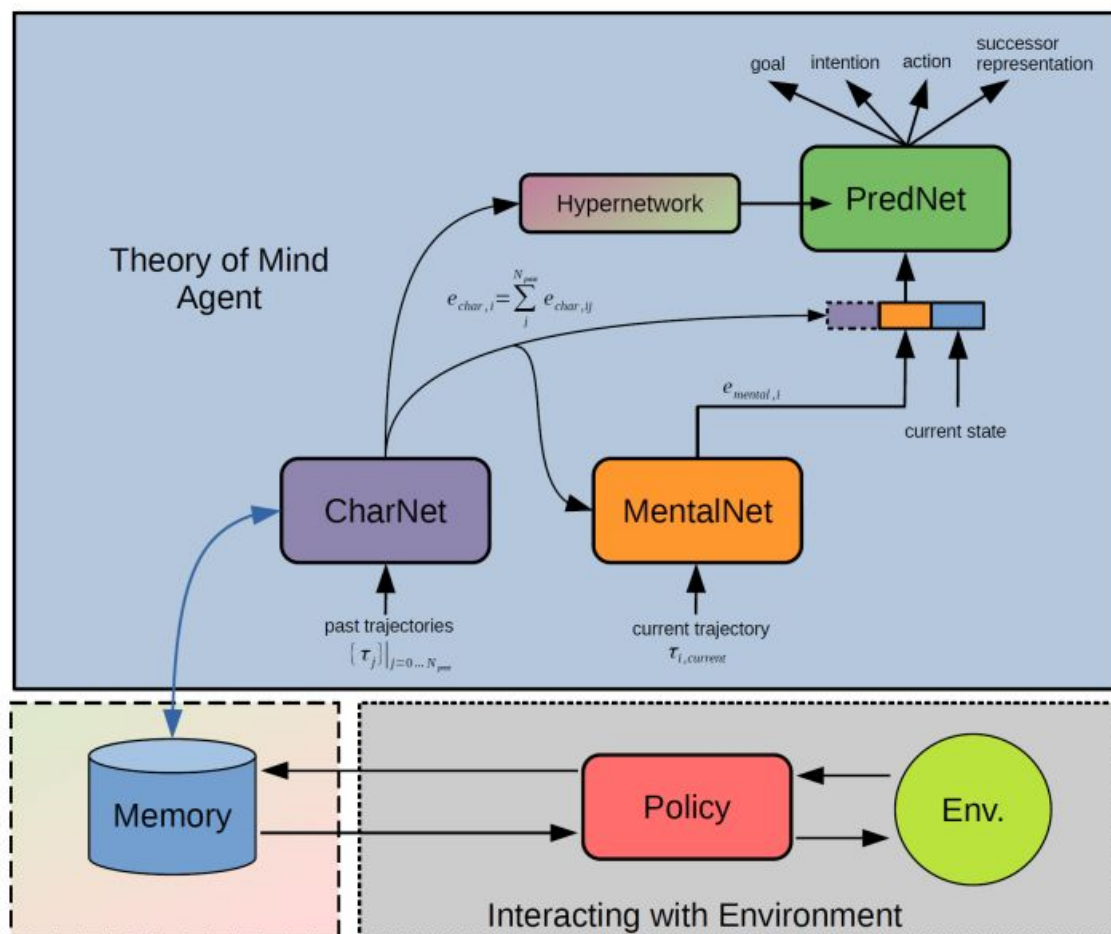


Figure 7. Using the ToMnet to characterise trained neural-net agents. (a) Usefulness of ToMnet components for the three behavioural prediction targets, compared with a simple ToMnet with no character nor mental net. Longer bars are better; including both character and mental nets is best. More details are given in Table A1. (b) A ToMnet’s prediction of agents’ future state occupancy given a query POMDP state at time $t = 0$ (left), as per Fig 4d. Star denotes the subgoal. The maps on the right are produced after observing behaviour on $N_{past} = 5$ past POMDPs from a sampled agent of each subspecies (always preferring the pink object). The ToMnet does not know a priori which subspecies each agent belongs to, but infers it from past behaviour.

A ToM architecture

- Observer maintains memory of previous episodes of the agent.
- It theorizes the “traits” of the agent.
 - Implemented as Hyper Networks.
- Given the current episode, the observer tries to infer goal, intention, action, etc of the agent.
 - Implemented as memory retrieval through attention mechanisms.



Agent57: Outperforming the Atari Human Benchmark

Adrià Puigdomènech Badia^{*1} Bilal Piot^{*1} Steven Kapturowski^{*1} Pablo Sprechmann^{*1}
Alex Vitvitskyi¹ Daniel Guo¹ Charles Blundell¹

Abstract

Atari games have been a long-standing benchmark in the reinforcement learning (RL) community for the past decade. This benchmark was proposed to test general competency of RL algorithms. Previous work has achieved good average performance by doing outstandingly well on many games of the set, but very poorly in several of the most challenging games. We propose Agent57, the first deep RL agent that outperforms the standard human benchmark on all 57 Atari games. To achieve this result, we train a neural network which parameterizes a family of policies ranging from very exploratory to purely exploitative. We propose an adaptive mechanism to choose which policy to prioritize throughout

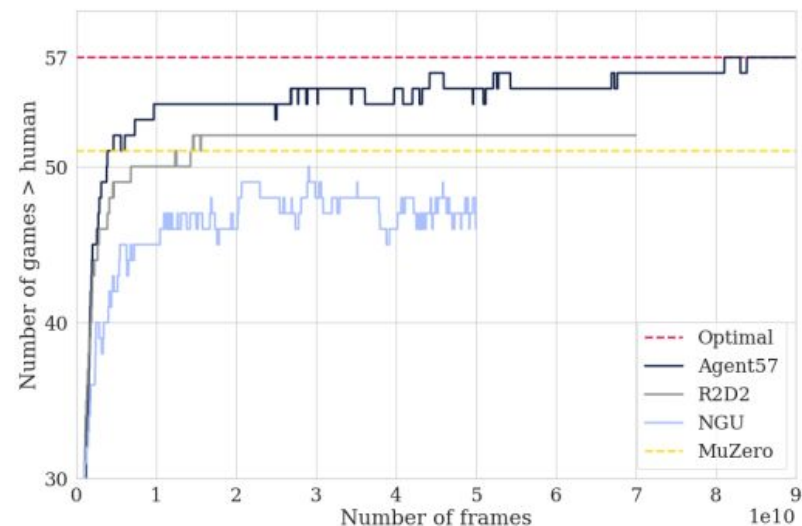
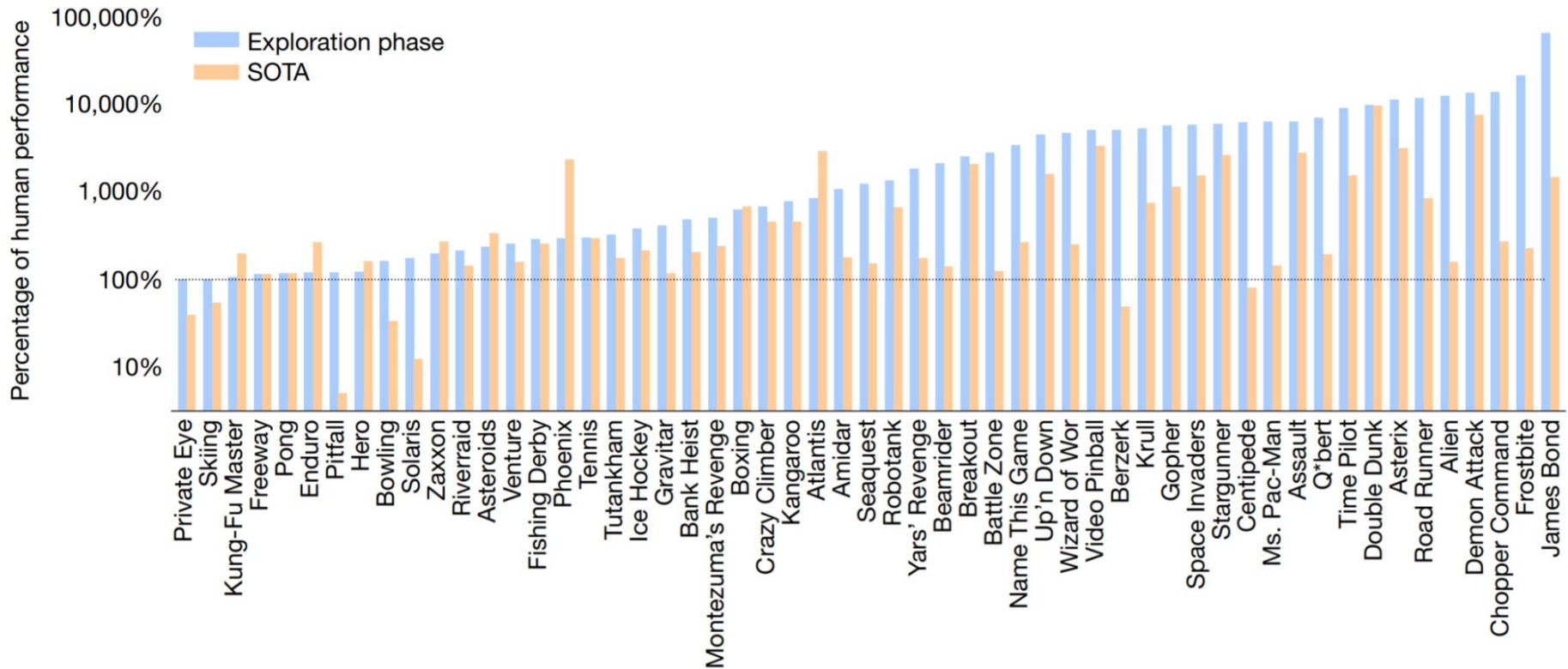


Figure 1. Number of games where algorithms are better than the human benchmark throughout training for Agent57 and state-of-the-art baselines on the 57 Atari games.

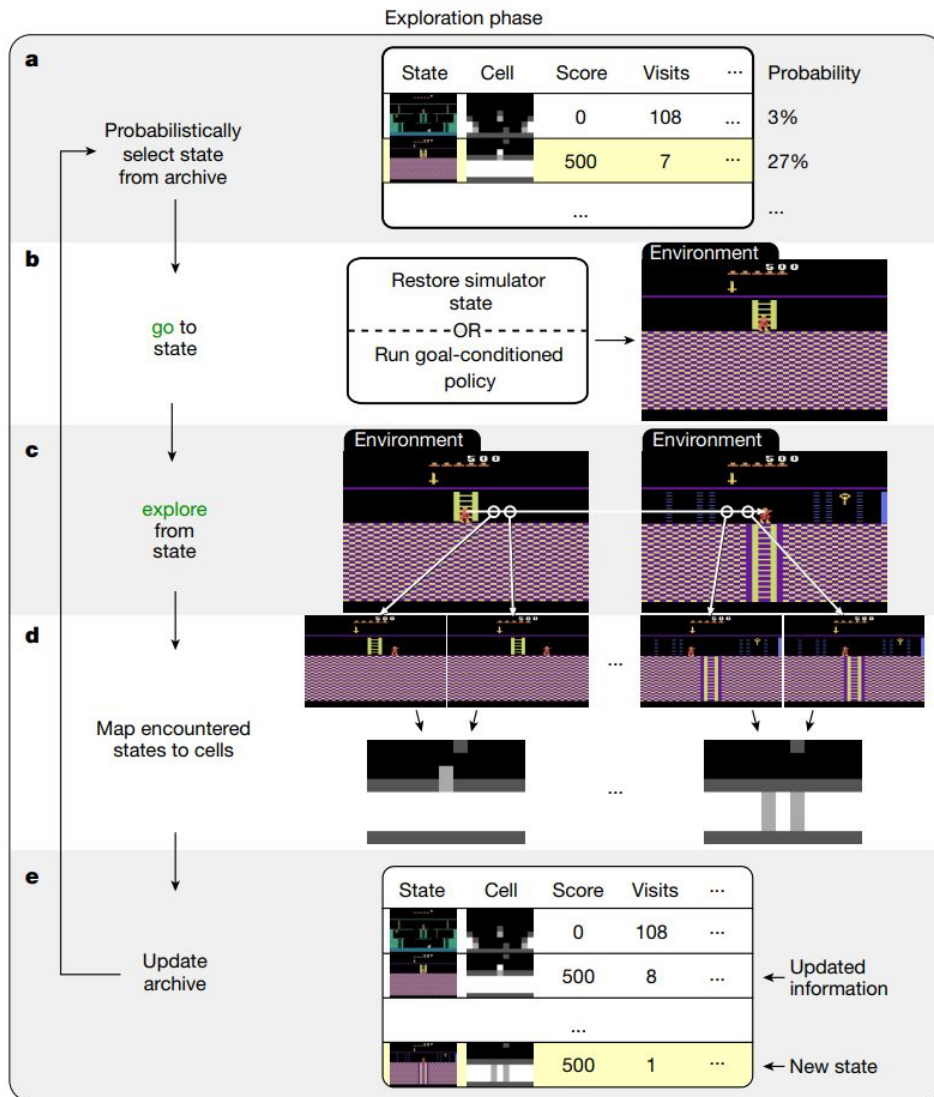
... we train a neural network which parameterizes a family of policies ranging from very exploratory to purely exploitative. We propose an adaptive mechanism to choose which policy to prioritize throughout the training process. ...

Human competitiveness of results



<https://www.nature.com/articles/s41586-020-03157-9.pdf>

First return then explore (2021)



- What if rewards provide sparse and deceptive feedback?
- We can explicitly 'remember' promising states and returning to such states before intentionally exploring

Reasoning with Language Model is Planning with World Model

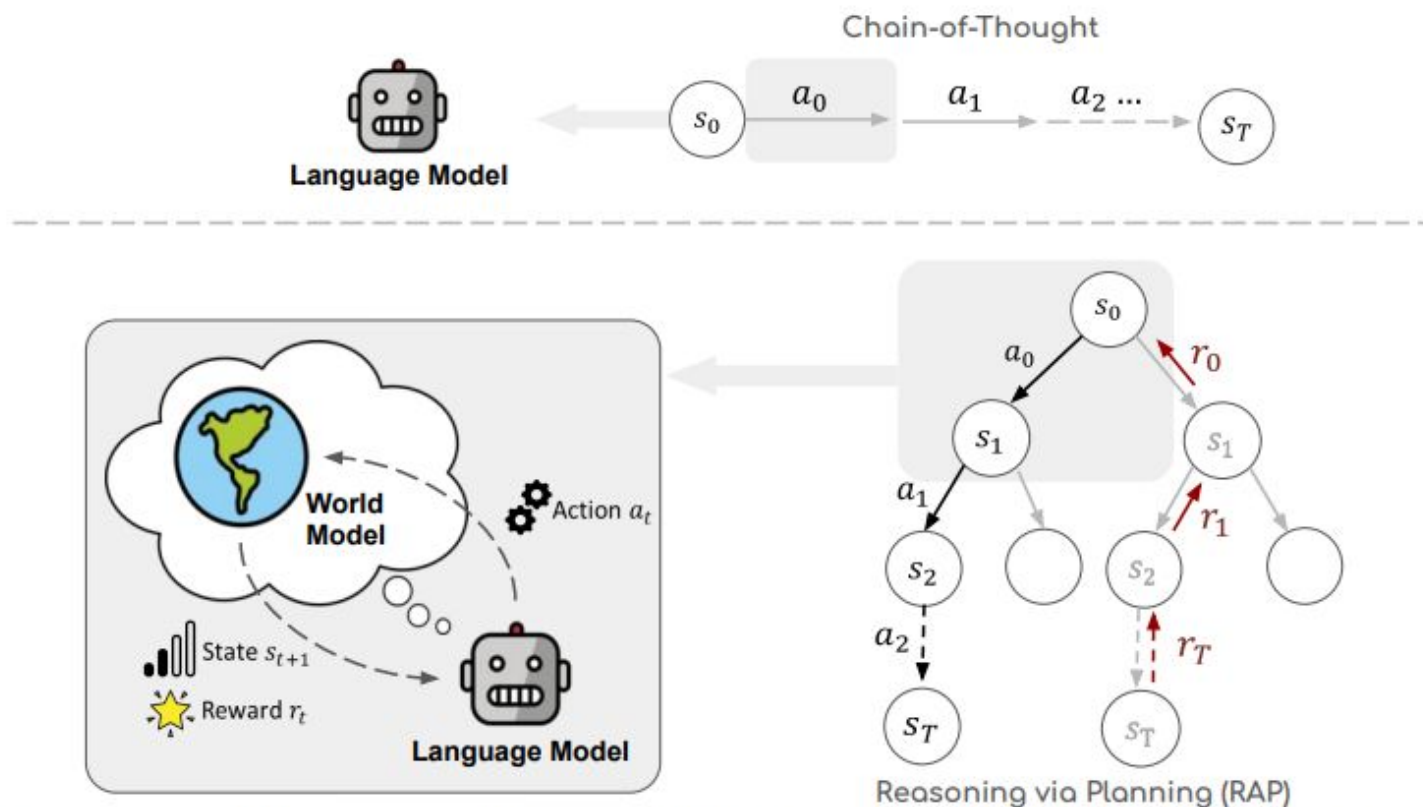


Figure 1: An overview of Reasoning via Planning (RAP). Compared with previous LLM reasoning methods like Chain-of-Thought (Wei et al., 2022), we explicitly model the world state from a world model (repurposed from the language model), and leverage advanced planning algorithms to solve the reasoning problems.

Fast open-ended environment for training reinforcement learning agents



Mining



Farming



Dungeon Crawling



Archery



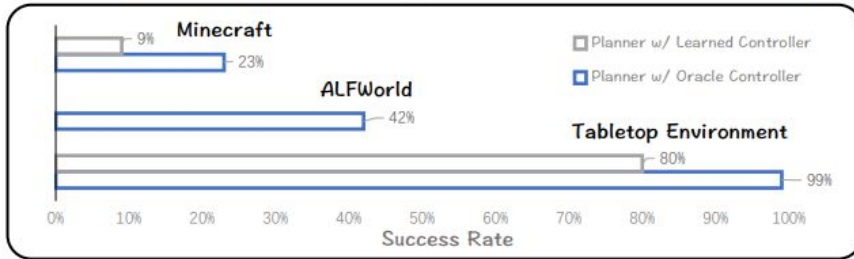
Building



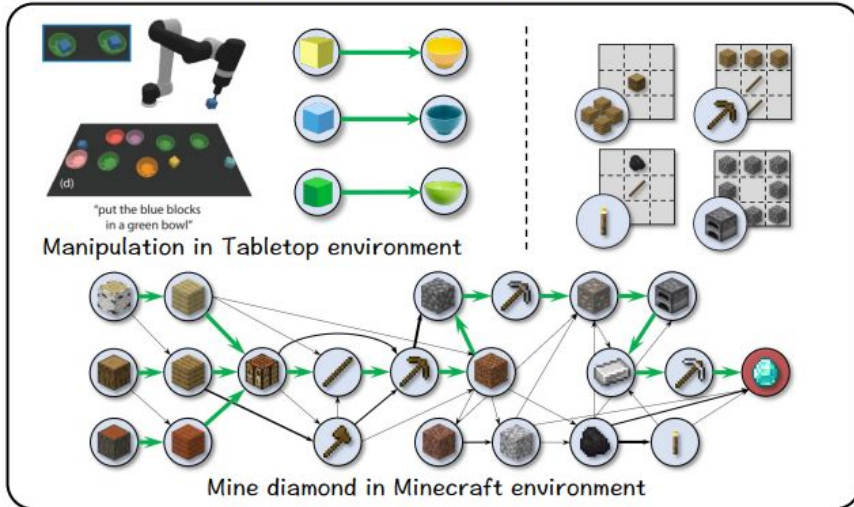
Magic

Describe, Explain, Plan and Select: LLMs Enables Open-World Multi-Task Agents

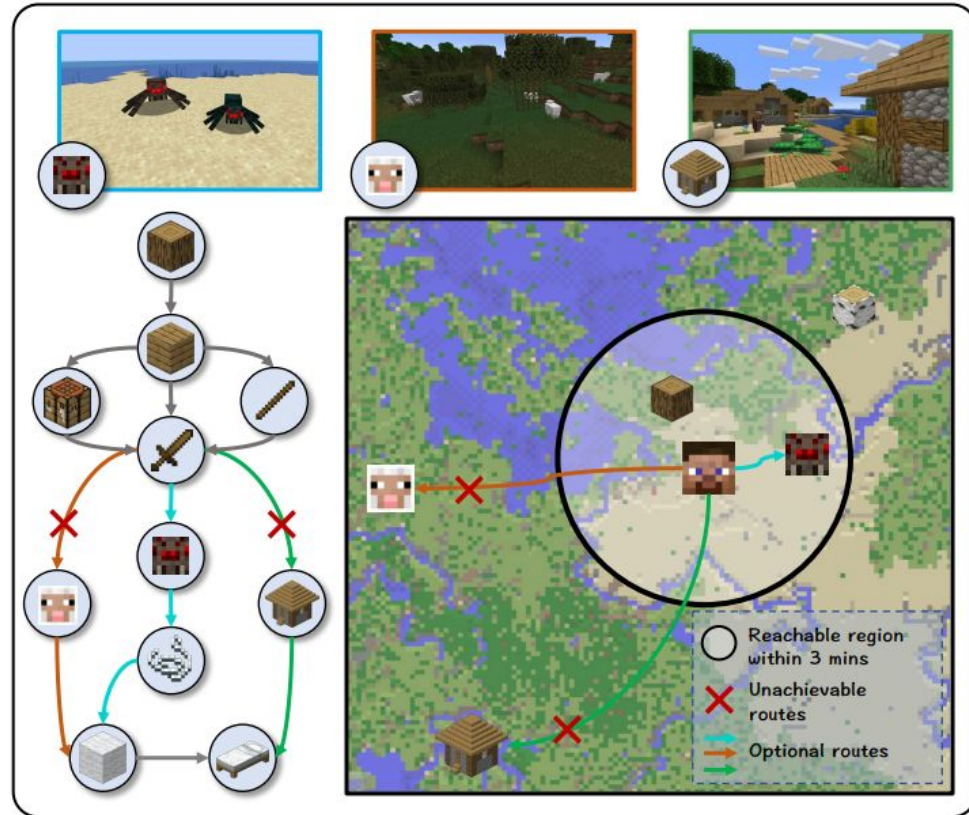
Planning success plummet in open worlds due to new challenges



Challenge #1: Complex Sub-task Dependency



Challenge #2: State-dependent Task Feasibility



DreamerV3: universal world models

<https://arxiv.org/pdf/2301.04104.pdf>

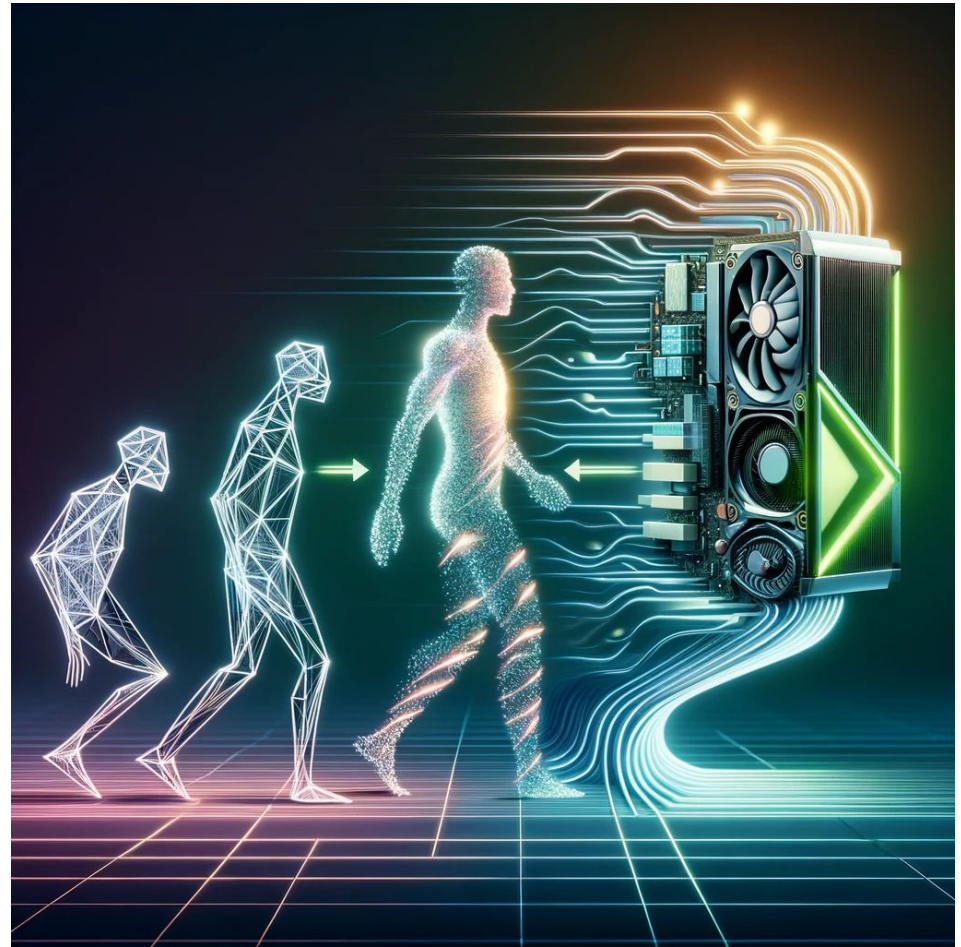
Google Genie: generating playable environments from single image



Zero shot world models of diverse environments: <https://arxiv.org/pdf/2402.15391v1.pdf>

Making AI systems affordable

Transforming
research prototypes
into production AI
systems that are
fast and can handle
millions of
concurrent users ...



Flash attention - accelerating transformers

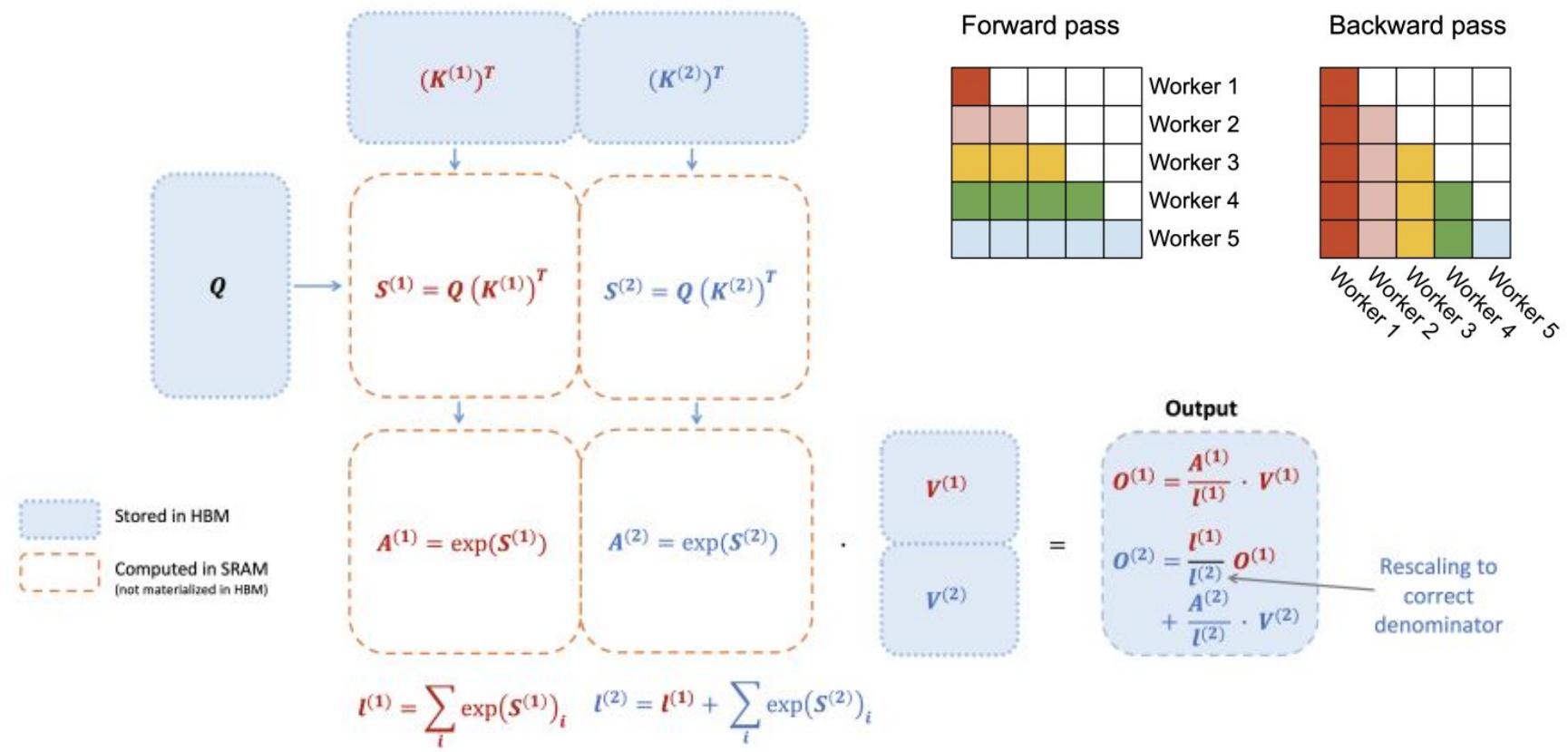


Figure 1: Diagram of how FLASHATTENTION forward pass is performed, when the key \mathbf{K} is partitioned into two blocks and the value \mathbf{V} is also partitioned into two blocks. By computing attention with respect to each block and rescaling the output, we get the right answer at the end, while avoiding expensive memory reads/writes of the intermediate matrices \mathbf{S} and \mathbf{P} . We simplify the diagram, omitting the step in softmax that subtracts each element by the row-wise max.

Ring attention

	Max context size supported ($\times 1e3$)				Ours vs SOTA
	Vanilla	Memory Efficient Attn	Memory Efficient Attn and FFN	Ring Attention (Ours)	
8x A100 NVLink					
3B	4	32	64	512	8x
7B	2	16	32	256	8x
13B	2	4	16	128	8x
32x A100 InfiniBand					
7B	4	64	128	4096	32x
13B	4	32	64	2048	32x
TPUv3-512					
7B	1	4	8	2048	256x
13B	1	2	8	1024	128x
TPUv4-1024					
3B	8	16	32	16384	512x
7B	4	8	16	8192	512x
13B	4	8	16	4096	256x
30B	2	4	8	2048	256x

LORA: LOW-RANK ADAPTATION OF LARGE LANGUAGE MODELS

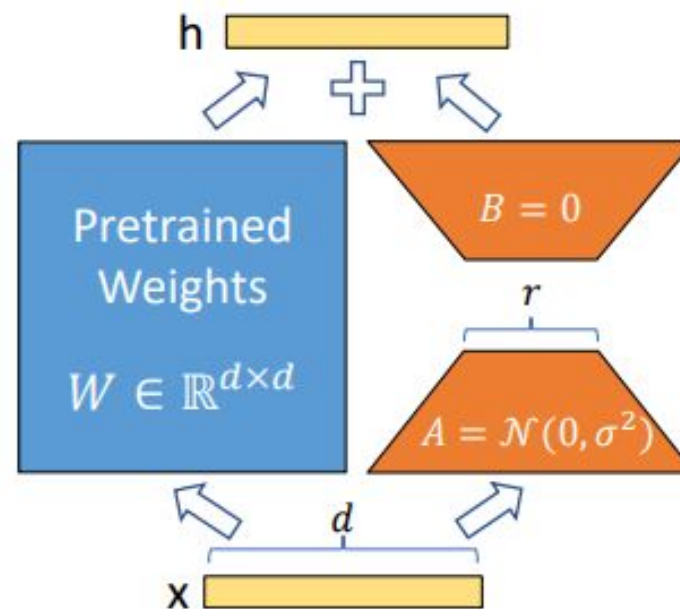


Figure 1: Our reparametrization. We only train A and B .

QLoRA for transformers

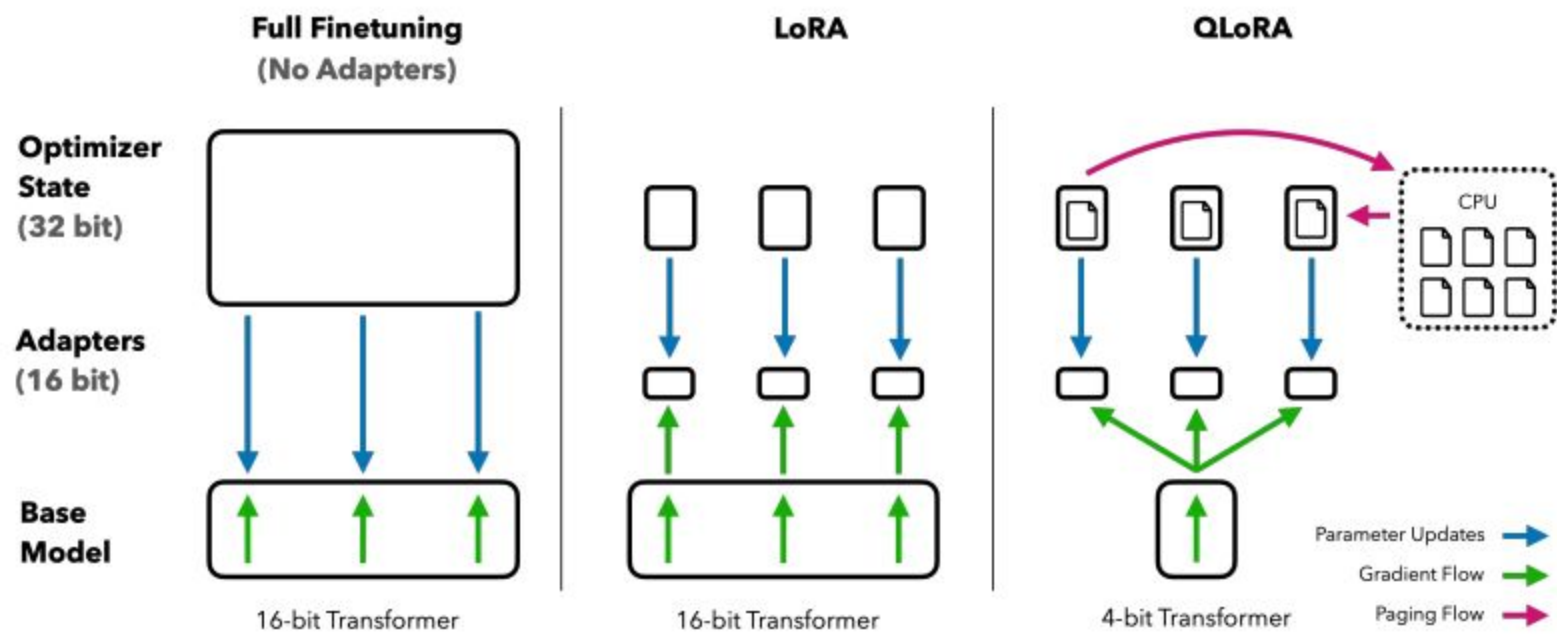


Figure 1: Different finetuning methods and their memory requirements. QLoRA improves over LoRA by quantizing the transformer model to 4-bit precision and using paged optimizers to handle memory spikes.

Decision Transformers with Internal Working Memory

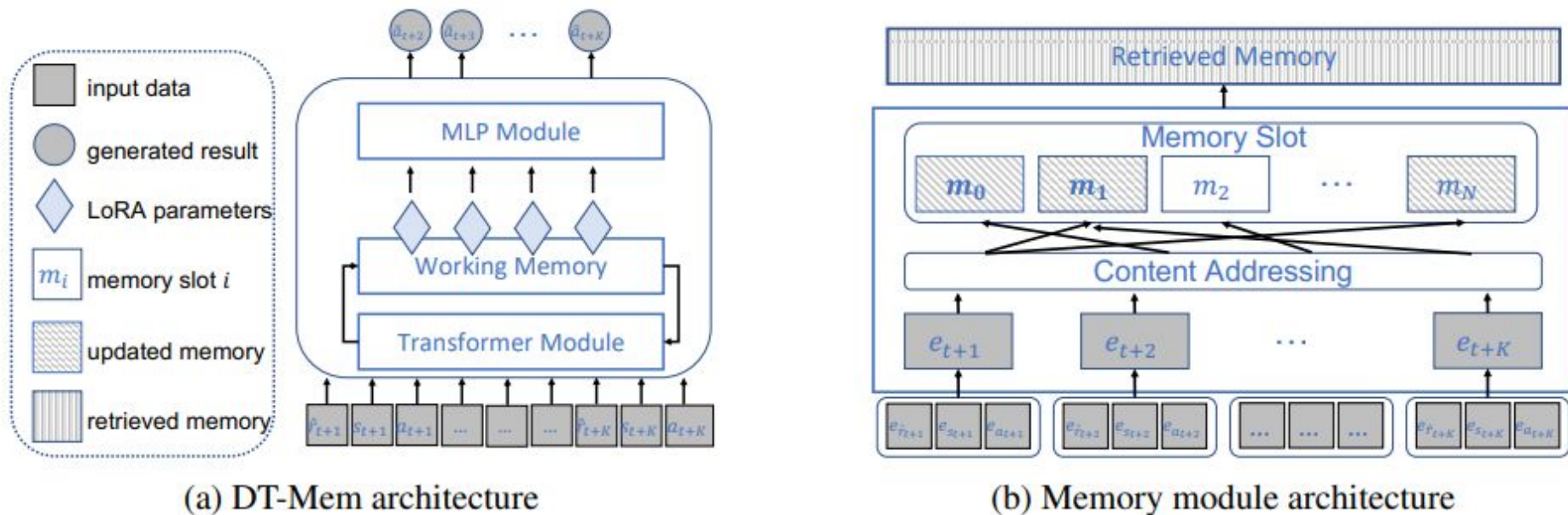
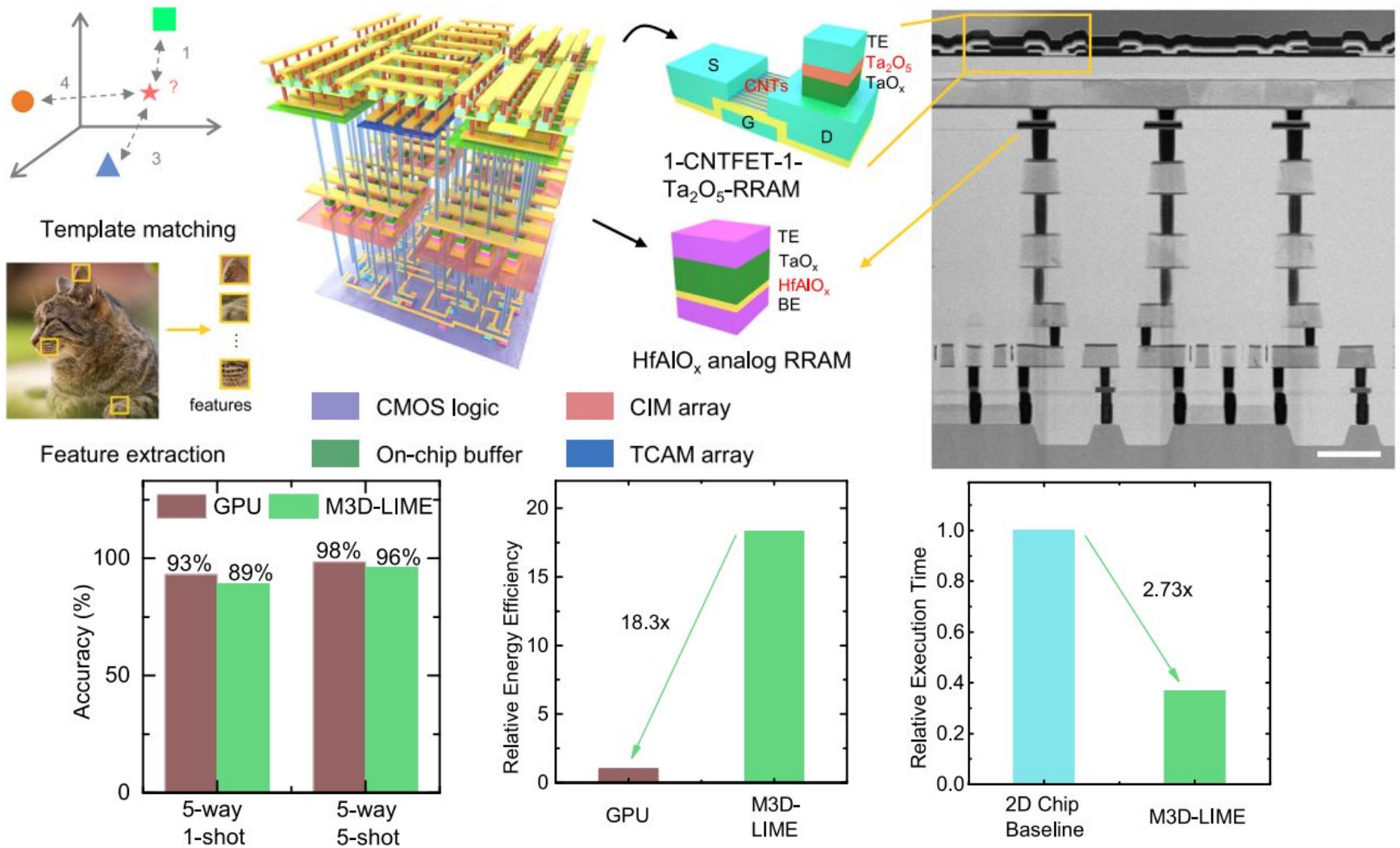


Figure 2: An overview of the proposed DT-Mem architecture. In 2a, Transformer module interact with working memory multiple times.

DT-Mem achieves better generalization on Atari games with only 10% of the model parameters compared to the state-of-the-art method.

Hardware acceleration in 3D



The classification accuracy of one-shot/few-shot learning on the Omniglot dataset using GPU and the M3D-LIME. The accuracy is the average of 5 randomly selected classes (5-way) in the dataset. Benchmark of the energy efficiency of the M3D-LIME chip and GPU. Benchmark of the execution time on the M3D-LIME and 2D chip baseline

Real world AI use cases



Autonomous driving

[Autopilot Review](#): Tesla and Elon Musk have placed a big target on delivering autonomous Full Self-Driving and even a [Tesla RoboTaxi service](#). By most accounts, that's extremely ambitious and it doesn't seem close-at-hand... yet.

That said, the latest [Full Self-Driving Beta](#) is showing some impressive improvements. Now with [Hardware 4](#) having launched in 2023 we should continue to see a steady pace of improvements to the Autopilot and Full Self-Driving experience. However, it's important to remember, it's likely still years away from being truly autonomous.

—

Police investigate after Waymo driverless car vandalized, set ablaze in SF's Chinatown



Planning-oriented Autonomous Driving

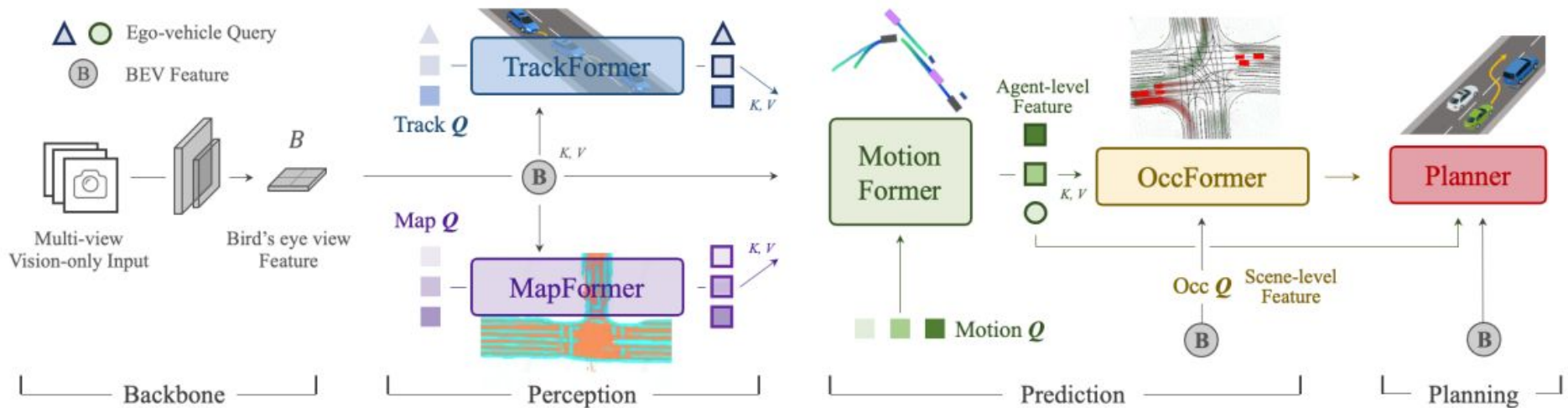


Figure 2. **Pipeline** of Unified Autonomous Driving (UniAD). It is exquisitely devised following planning-oriented philosophy. Instead of a simple stack of tasks, we investigate the effect of each module in perception and prediction, leveraging the benefits of joint optimization from preceding nodes to final planning in the driving scene. All perception and prediction modules are designed in a transformer decoder structure, with task queries as interfaces connecting each node. A simple attention-based planner is in the end to predict future waypoints of the ego-vehicle considering the knowledge extracted from preceding nodes. The map over occupancy is for visual purpose only.

https://openaccess.thecvf.com/content/CVPR2023/papers/Hu_Planning-Oriented_Autonomous_Driving_CVPR_2023_paper.pdf

A Generative World Model for Autonomous Driving

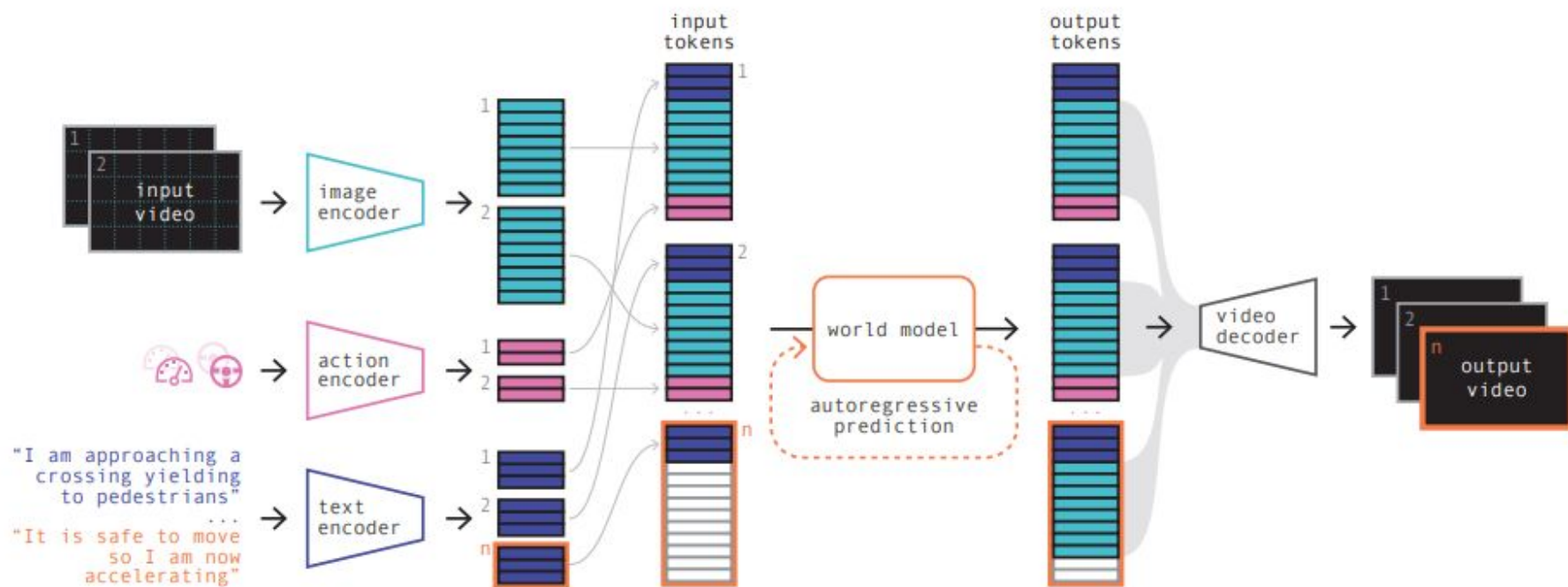
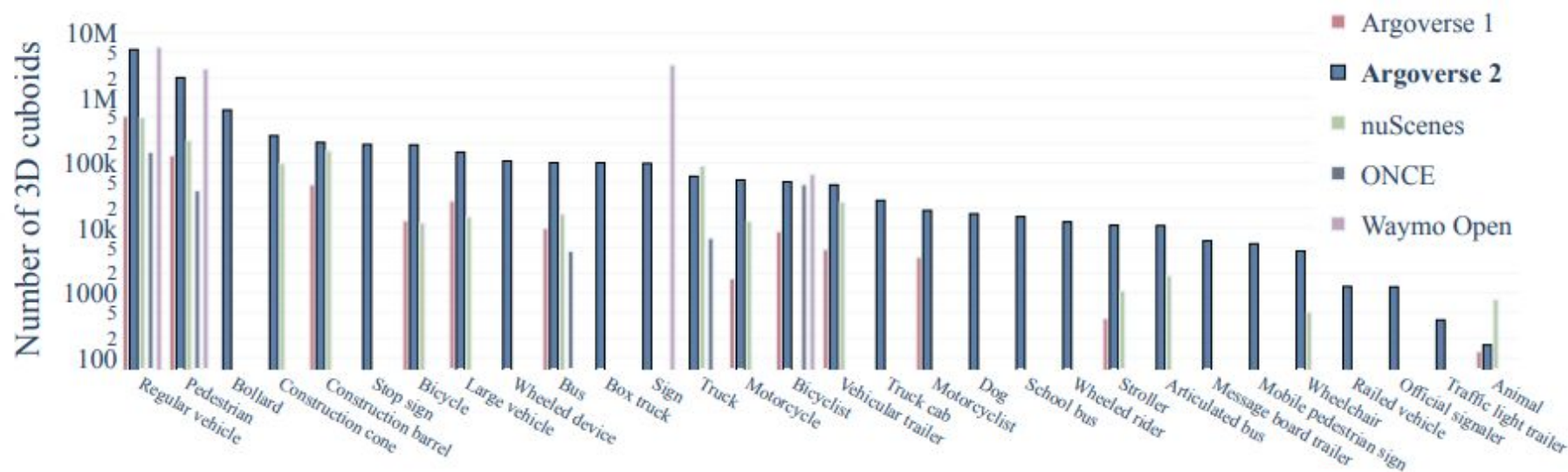


Figure 2: Architecture of GAIA-1. First, we encode information from all input modalities (video, text, action) into a common representation: images, text and actions are encoded as a sequence of tokens. The world model is an autoregressive transformer that predicts the next image token conditioned on past image, text, and action tokens. Finally, the video decoder maps the predicted image tokens back to the pixel space, at a higher temporal resolution.

Argoverse 2: Next Generation Datasets for Self-Driving Perception and Forecasting

Table 1: Comparison of the Argoverse 2 *Sensor* and *Lidar* datasets with other sensor datasets.

Name	# Scenes	Cities	Lidar?	# Cameras	Stereo	HD Maps?	# Classes	# Evaluated Classes
Argoverse 1 [6]	113	2	✓	7	✓	✓	15	3
KITTI [17]	22	1	✓	2	✓		3	3
nuScenes [4]	1,000	2	✓	6		✓	23	10
ONCE [36]	581	–	✓	7			5	3
Waymo Open [45]	1,150	3	✓	5			4	4
Argoverse 2 Sensor	1,000	6	✓	9	✓	✓	30	26
Argoverse 2 Lidar	20,000	6	✓	-		✓	-	-



LLM search and recommendations



Given a natural query, return items from catalog relevant for given user ...













Describe who you're shopping for ⓘ

my wife who likes baking 🔍

Set a budget

\$1 No Limit

No Limit

 <p>Nordic Ware Blossom Bundt Pan, Brown</p> <p>\$31.04 \$39</p> <p>Home Depot</p>	 <p>Staub Ceramics 4-pc Baking Pans Set, Casserole Dish with Lid...</p> <p>\$99.95 \$136</p> <p>Amazon</p>	 <p>Nordic Ware 12 Cup Formed Aluminum Bundt Pan Blue with Cake...</p> <p>\$21.99 \$28</p> <p>Target</p>	 <p>Cuisinart - Chef's Classic 17" Baking Sheet - Stainless-Steel</p> <p>\$17.49 \$20</p> <p>Best Buy</p>	 <p>Emily Post's Wedding Planner for Moms - by Peggy Post (Hardcover)</p> <p>\$16.19 \$21</p> <p>Target</p>	 <p>ZWILLING</p> <p>Zwilling: a Free Gift (up to \$59 value) when you spend \$149+ + Free...</p> <p>Zwilling J.A. Henckels</p>
 <p>Costway Tilt-Head Stand Mixer 6.3 or 7.5 Qt 6 Speed stand mixer...</p> <p>Walmart</p>	 <p>Caraway 11-piece Ceramic Non-Stick Cookware & Bakeware...</p> <p>\$399.99</p> <p>Costco Wholesale</p>	 <p>Chicago Metallic 16833 Professional Non-Stick Cookie/Jelly-Roll Pan S...</p> <p>\$17.58 \$23</p> <p>Amazon</p>	 <p>KitchenAid Artisan 10-Speed Stand Mixer - Hearth & Hand™ with...</p> <p>\$334.99 \$379</p> <p>Target</p>	 <p>Courant 5-Speed White Hand Mixer with Eject Button</p> <p>\$24.27 \$28</p> <p>Home Depot</p>	 <p>5.5-Quart Lodge Cast Iron Enameled Dutch Oven w/ Lid (Red, Blue ...</p> <p>\$40 \$47</p> <p>+ Free Shipping</p> <p>Walmart</p>

Refining SBERT-based Semantic Search: Ethical Controls and Content Precision

3 Data and model

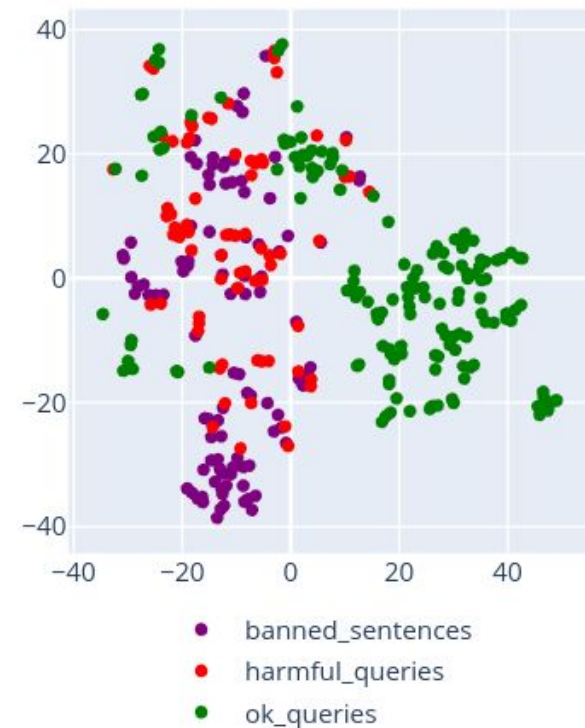
Data for training the SBERT model were obtained from the client. The various queries used for testing the ethical filters were designed by the author, using several sources such as [2] or [1].

The SBERT model is derived from a pre-trained general MPNetModel from the SentenceTransformers library. It was then trained using the data provided by the customer to better perform on this specific task. It outputs 512-dimensional embedding vectors.

4 Ethical controls and content precision

The idea of ethical control is the follows: Create a list of banned sentences, that would cover harmful topics. If a query similarity to some banned sentence is higher than a given threshold, it should be ignored. To measure the similarity between two queries, it is first necessary to get the embedding vectors. These can be obtained using the trained

Queries and banned sentences



Personal assistants



Memory-augmented Dialogue Management for Task-oriented Dialogue Systems

<https://arxiv.org/pdf/1805.00150.pdf>

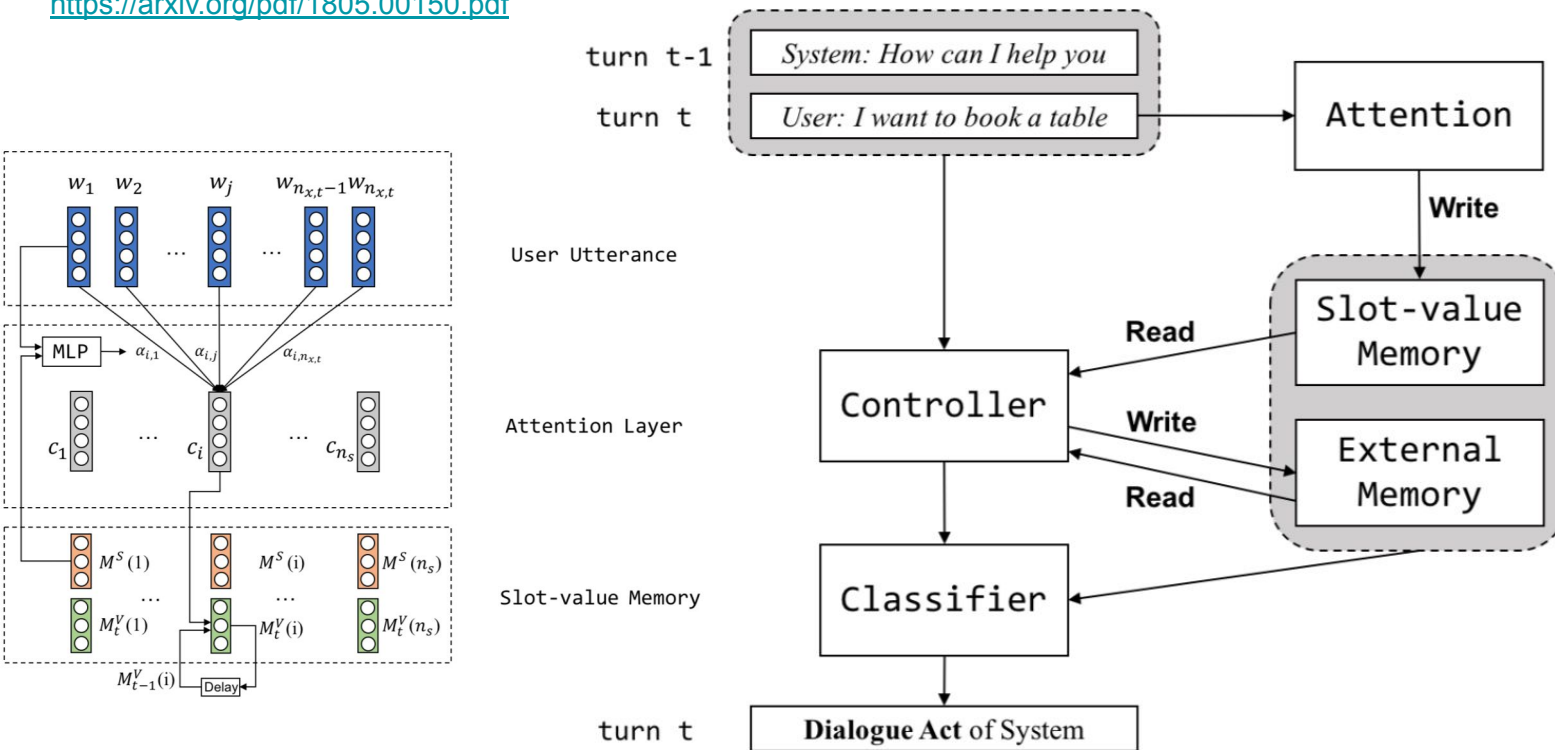


Fig. 3. Memory-augmented Dialogue Management (MAD): At each dialogue turn t , the model takes as input the current user utterance and the previous system response, and predicts the next dialogue act. The slot-value memory is updated with an attentive read of the user utterance by a slot-level attention mechanism while the external memory is read and updated by the controller. The memory controller along with the two memory modules will predict the next dialogue act of the system by a classifier.

Memory-Augmented LLM Personalization with Short- and Long-Term Memory Coordination

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Abstract

Large Language Models (LLMs), such as GPT3.5, have exhibited remarkable proficiency in comprehending and generating natural language. However, their unpersonalized generation paradigm may result in suboptimal user-specific outcomes. Typically, users converse differently based on their knowledge and preferences. This necessitates the task of enhancing user-oriented LLM which remains unexplored. While one can fully train an LLM for this objective, the resource consumption is unaffordable. Prior research has explored memory-based methods to store and retrieve knowledge to enhance generation without retraining for new queries. However, we contend that a mere memory module is inadequate to comprehend a user's preference, and fully training an LLM can be excessively costly. In this study, we propose a novel computational bionic memory mechanism, equipped with a parameter-efficient fine-tuning schema, to personalize LLMs. Our extensive experimental re-

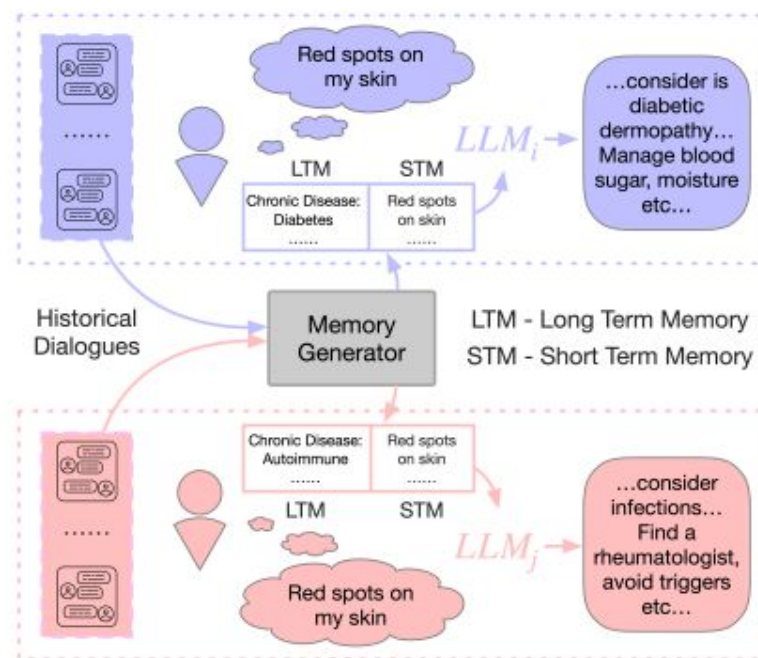


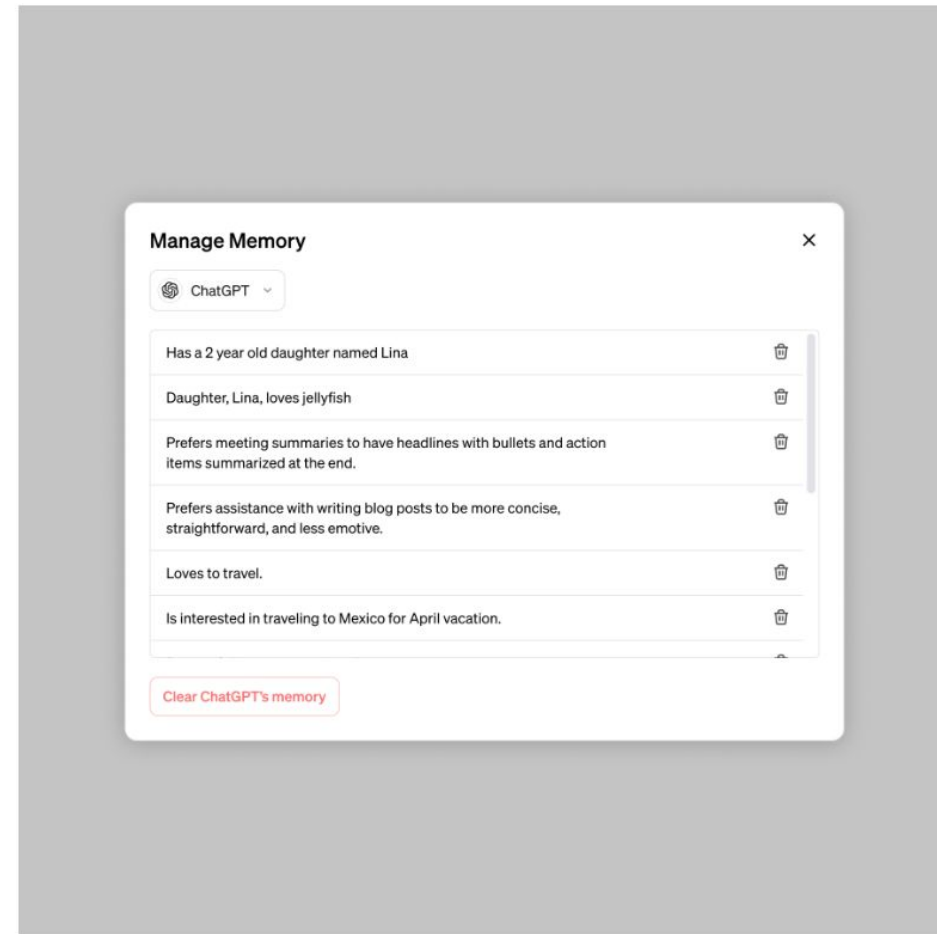
Figure 1: Personalized responses for different users in terms of memory coordination

AI Assistants getting personal

Memory and new controls for ChatGPT

We're testing the ability for ChatGPT to remember things you discuss to make future chats more helpful. You're in control of ChatGPT's memory.

February 13, 2024



<https://openai.com/blog/memory-and-new-controls-for-chatgpt>

AI4kids (non profit) personalized learning app

- LLMs as personal tutors?
- LLMs evaluating teaching progress?
- LLMs generating learning tasks for children?
- How to help both kids and teachers?
- How to make AI safe for kids?

First results: https://github.com/slavivo/open_evaluation

Who is interested? Let me know! I am looking for advisory board member with experience in AI safety.

Integrating AI Assistants into Classroom Learning

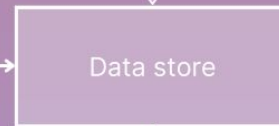


Technical concept

Interface for both teachers and kids. They interact with Tiny app, which records user feedback, responses, and interactions.



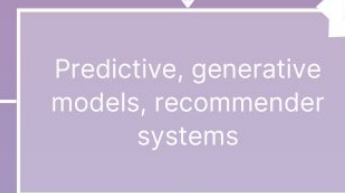
This is a database or repository for data including user profiles and history, questions, answers, and the curriculum. Data collected from the app are stored here.



AI utilizes the data from the data store to create predictive, generative models and recommender systems to help tailor educational content.



Templates can be created by editors or generated by AI models.



For example generative model transforming one topic into set of activities and questions.



MVP—basic roadmap 2024



Research in schools

	April	May	June	July	August	September	November	December	
Student part	POC prototype (dumb) <ul style="list-style-type: none"> • manual preparation of exercise for the first part of curriculum • based on existing tools (questionnaires etc.) • data collection • custom build POC using low code 		Prototype testing <ul style="list-style-type: none"> • in schools 	Reflection & self-evaluation <ul style="list-style-type: none"> • reflective conversation design • questions to support self-evaluation 		Reflection & self-evaluation part testing	Putting all parts together	FINAL MVP prototype	
	Knowledge validation <ul style="list-style-type: none"> • how to generate questions? AI vs. humans 		MVP design (student's part) <ul style="list-style-type: none"> • pre-final stage 						
Teacher part			POC prototype (dumb) <ul style="list-style-type: none"> • similar to student part 		Prototype testing <ul style="list-style-type: none"> • similar to student part 				
Research POC	AI research POC for student part (AI tutor) <ul style="list-style-type: none"> • research will continue throughout the duration of the project 		AI research POC for teachers part (AI teaching assistant) <ul style="list-style-type: none"> • research will continue throughout the duration of the project 						

POC—research proof of concept focusing on AI technologies that enable the MVP to be scalable and applicable in school learning environments; in particular, we need to take the first steps towards an AI tutor for kids and an AI teaching assistant for teachers.

Possible research topics: generating good questions for students given an educational material, task or activity to assess their understanding; evaluating students' answers and extracting their learning progress, giving appropriate feedback, presenting learning progress of individual kids to the teacher, notifying the teacher that some kid needs attention

Other interesting papers

ChatGPT: <https://arxiv.org/pdf/2206.02336.pdf>

<https://arxiv.org/pdf/2206.07699.pdf>

<https://arxiv.org/pdf/2201.11903.pdf>

PALM: <https://arxiv.org/pdf/2204.02311.pdf>

GATO: <https://arxiv.org/pdf/2205.06175.pdf?fs=e&s=cl>

Model free RL: <https://arxiv.org/pdf/2208.07860.pdf>

Diffusion world models: <https://arxiv.org/pdf/2402.03570.pdf>

Mamba: <https://openreview.net/forum?id=AL1fq05o7H>

Codelt: <https://arxiv.org/pdf/2402.04858.pdf>

Algorithm discovery:

<https://www.nature.com/articles/s41586-023-06887-8>

<https://www.jmlr.org/papers/volume24/21-0449/21-0449.pdf>

Thanks for attention



<https://open.substack.com/pub/pavelkordik/p/latest-ai-developments-explained>

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